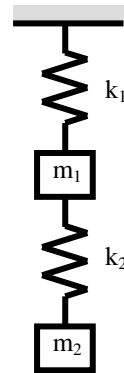


Name: _____

You are allowed 3 sheets of notes.

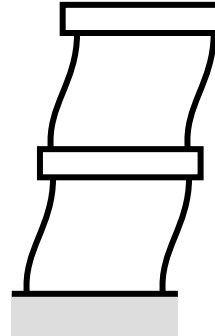
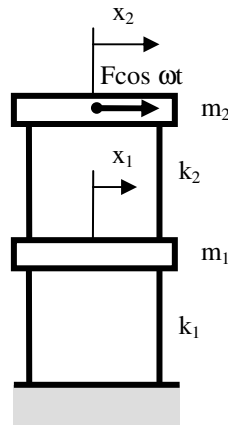
1. For the system shown on the right, solve for:
- system differential equation(s)
 - natural frequencies
 - mode shapes



$$\begin{aligned} m_1 &= 100 \text{ kg} \\ m_2 &= 1 \text{ kg} \\ k_1 &= 1000 \text{ N/m} \\ k_2 &= 100 \text{ N/m} \end{aligned}$$

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2. An air conditioning system is being installed on the roof of a two-story building. The fan causes a harmonic lateral force of $50 \cos 20t$ N due to a rotating imbalance in the fan. If the masses of the floors and lateral stiffness of the support columns are as given, find:
- system differential equation(s)
 - $\mathbf{x}(t)$

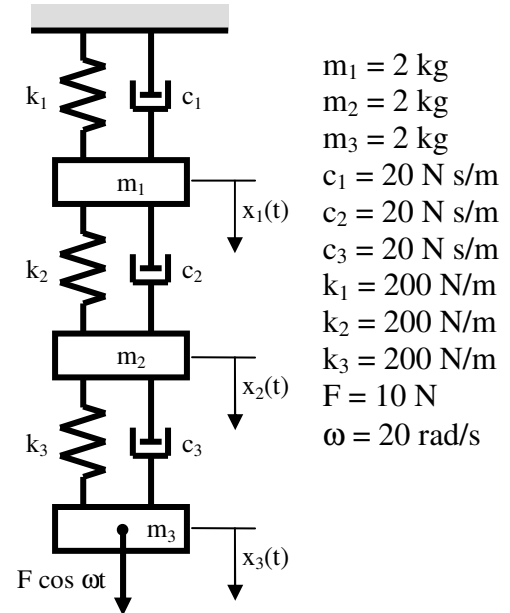


$$\begin{aligned} m_1 &= 1 \times 10^4 \text{ kg} \\ m_2 &= 3 \times 10^4 \text{ kg} \\ k_1 &= 2 \times 10^5 \text{ N/m} \\ k_2 &= 2 \times 10^5 \text{ N/m} \\ F &= 50 \text{ N} \\ \omega &= 20 \text{ rad/s} \end{aligned}$$

Use the “Direct Method” to compute the particular solution only. Note that you will need to solve a 2 dof linear system of equations. If you do not have a matrix calculator, in the first equation solve for x_1 as a function of x_2 (or vice versa) and substitute into the second equation.

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3. For the system shown on the right, using the “Direct Method,” solve for:
- system differential equation(s)
 - mass, damping and stiffness matrices
 - single 6x6 matrix that can be used to solve for \mathbf{X}_1 and \mathbf{X}_2 in $\mathbf{x}(t) = \mathbf{X}_1 \cos \omega t + \mathbf{X}_2 \sin \omega t$.



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4. (a) In a modal analysis, what are two ways of handling damping?

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(b) What is a “node” in a mode shape?

(c) How is the modal analysis technique different than the direct method when solving for harmonic forced vibration?

5. A single-degree-of-freedom system has a mass of 2 kg, spring stiffness of 200 N/m and viscous damping of 20 N·s/m. Give:
- a) System differential equation
 - b) Damping condition (underdamped, overdamped, or critically damped)
 - c) Stability (stable or unstable)
 - d) Correct equation to be used for $x(t)=\dots$ and correct equations to be used for computing constants in this equation.
 - e) Displacement as a function of time for initial conditions $x(0) = 10$ mm and $\dot{x}(0) = 0$.

Problem 1 continued.

6. A single-degree-of-freedom system has a mass of 50 kg, spring stiffness of 500 N/m and viscous damping of 30 N·s/m. The floor supporting the mass (via the spring and damper) has a harmonic motion with amplitude 10 mm at a frequency of 1 Hz. Give:
- a) System differential equation
 - b) Damping condition (underdamped, overdamped, or critically damped)
 - c) Stability (stable or unstable)
 - d) Correct equation to be used for $x(t)=\dots$ and correct equations to be used for computing constants in this equation. (Assume all free vibration has been damped out.)
 - e) Amplitude of the displacement
 - f) Amplitude of the velocity
 - g) Amplitude of the acceleration
 - h) Amplitude of the transmitted force.

Problem 2 continued.