

# Base Excitation

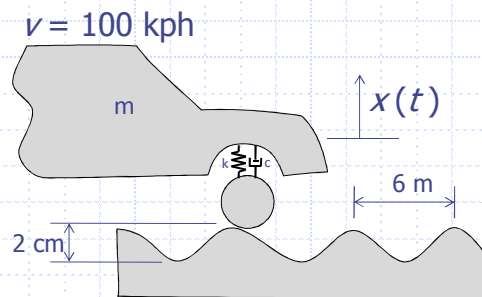
## Section 2.4

(Skipping Section 2.3)

## Vehicle traveling down bumpy road

- Given:

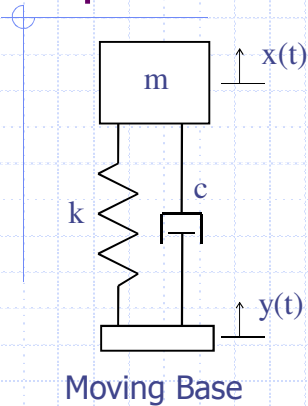
- $m = 1007 \text{ kg}$
- $k = 4 \times 10^5 \text{ N/m}$
- $c = 20 \times 10^3 \text{ Ns/m}$



- Find:

- Amplitude of steady-state vibration:  $X$
- Amplitude of transmitted force:  $F_T$

## Equations of Motion for Moving Base



Free body diagram

## Equations of Motion for Moving Base

If  $y(t) = Y \sin \omega t$   
and  $\dot{y}(t) = \omega Y \cos \omega t$

then

$$m\ddot{x} + c\dot{x} + kx = cY\omega \cos \omega t + kY \sin \omega t$$

or

$$\ddot{x} + 2\zeta\omega_n \dot{x} + \omega_n^2 x = 2\zeta\omega_n \omega Y \cos \omega t + \omega_n^2 Y \sin \omega t$$

## Solving the Differential Equation

- Solving in the same way as for  $F_0 \cos \omega t$  yields:

$$x_p(t) = \frac{2\zeta\omega_n\omega Y}{\sqrt{(\omega_n^2 - \omega^2)^2 + (2\zeta\omega_n\omega)^2}} \cos(\omega t - \theta_1) \\ + \frac{\omega_n^2 Y}{\sqrt{(\omega_n^2 - \omega^2)^2 + (2\zeta\omega_n\omega)^2}} \sin(\omega t - \theta_1)$$

where:  $\theta_1 = \tan^{-1} \left( \frac{2\zeta\omega_n\omega}{\omega_n^2 - \omega^2} \right)$

## Solving the Differential Equation

$$x_p(t) = \omega_n Y \left[ \frac{\omega_n^2 + (2\zeta\omega)^2}{(\omega_n^2 - \omega^2)^2 + (2\zeta\omega_n\omega)^2} \right]^{1/2} \cos(\omega t - \theta_1 - \theta_2)$$

where:  $\theta_2 = \tan^{-1} \left( \frac{\omega_n}{2\zeta\omega} \right)$

## Solving the Differential Equation

- Final Equation (for **base excitation** without free vibration):

$$x_p(t) = X \cos(\omega t - \theta_1 - \theta_2)$$

where:

$$X = Y \left[ \frac{1 + (2\zeta r)^2}{(1 - r^2)^2 + (2\zeta r)^2} \right]^{1/2}$$

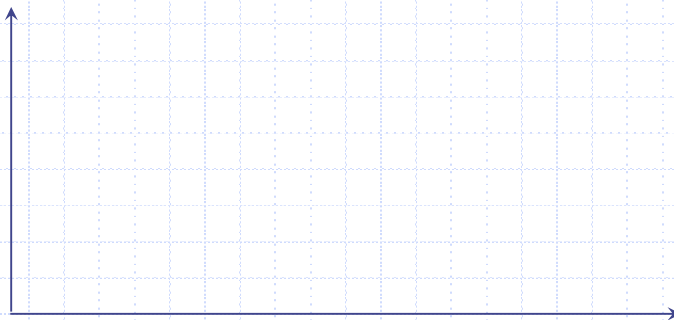
$$\theta_1 = \tan^{-1} \left( \frac{2\zeta r}{1 - r^2} \right)$$

$$\theta_2 = \tan^{-1} \left( \frac{1}{2\zeta r} \right)$$

$$r = \frac{\omega}{\omega_n}$$

## Plotting the “Displacement Transmissibility”

- Looking at just the steady-state vibration  $x_p(t)$ , we can plot the ratio of the amplitude  $X$  versus the amplitude  $Y$  as a function of base frequency  $\omega$ .



## How much force is transmitted?

$$F(t) = k(x - y) + c(\dot{x} - \dot{y}) = -m\ddot{x}(t)$$

$$-m\ddot{x}(t) = -m \frac{d^2 x_p(t)}{dt^2} = m\omega^2 Y \left[ \frac{1 + (2\zeta r)^2}{(1 - r^2)^2 + (2\zeta r)^2} \right]^{1/2} \cos(\omega t - \theta_1 - \theta_2)$$

- **Final equation** (for **transmitted force** due to steady-state vibration):

$$F(t) = F_T \cos(\omega t - \theta_1 - \theta_2)$$

$$F_T = kYr^2 \left[ \frac{1 + (2\zeta r)^2}{(1 - r^2)^2 + (2\zeta r)^2} \right]^{1/2}$$

## Plotting the “Force Transmissibility”

- Looking at just the forced vibration  $x_p(t)$ , we can plot the ratio of the amplitude of the dynamic transmitted force  $F_T$  versus the static force  $kY$  as a function of base frequency  $\omega$ .

