
Modeling Errors and Accuracy

And checking the results!

Sources of Error

Causes of incorrect results:

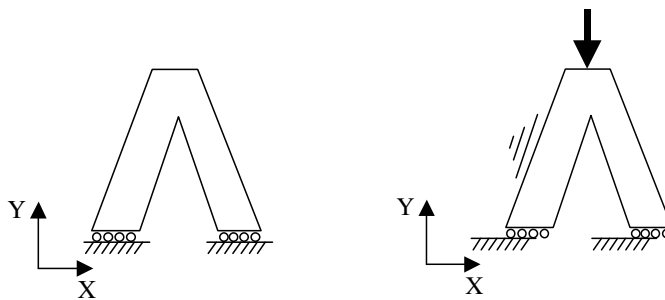
1. Mistakes (e.g., forgetting a load)
2. Errors
 - A. Modeling Error (due to simplifying assumptions in mathematical model such as when using beam elements we assume that the cross-sections stay planar and do not change shape)
 - B. Discretization Error (i.e., due to piecewise approximation which can be minimized by using higher order shape functions or smaller elements)
 - C. Numerical Error (due to limited number of significant digits maintained by computer)

1. Mistakes

- Common mistakes that will cause a singular \mathbf{K} matrix (and therefore no results):
 - $\nu = 0.5$ in a plain strain, axisymmetric or 3D solid element
 - $E = 0$ in an element
 - No supports, or **insufficient supports**
 - Part of the model is a **mechanism**
 - Large **stiffness differences**
 - In an element with stress-stiffening, negative stiffening has reduced the stiffness to zero
 - In nonlinear analysis, supports or connections have reached zero stiffness

Common Mistakes

- Insufficient supports will allow rigid body motion.



(The stiffness matrix will be singular.)

Common Mistakes

- Mistakes that may go unnoticed:
 - Incorrect **element** data (e.g., wrong thickness, beam cross-section, cross-section dimension, beam orientation)
 - **Supports** wrong in location, type or direction
 - **Loads** wrong in location, type, direction or magnitude
 - **Units** mix-up
 - A force or mesh defined twice and/or on different duplicated geometry
 - Connections not working as intended (e.g. beam element connected to plane element does not transfer moment)

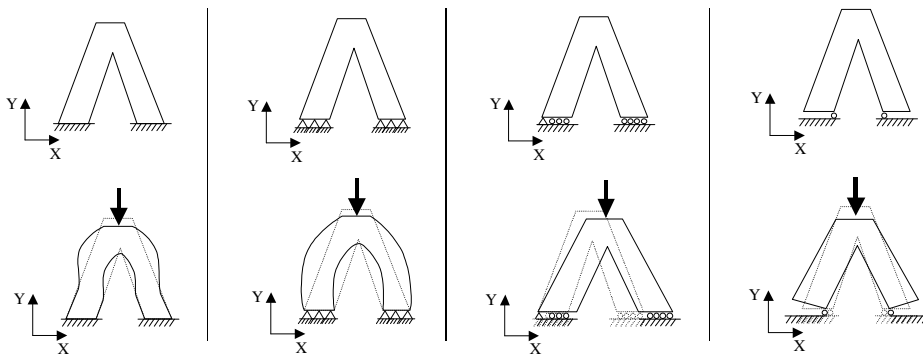
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Common Mistakes

- Effect of wrong support types:



Each of these will result in different displacements, strains and stresses.

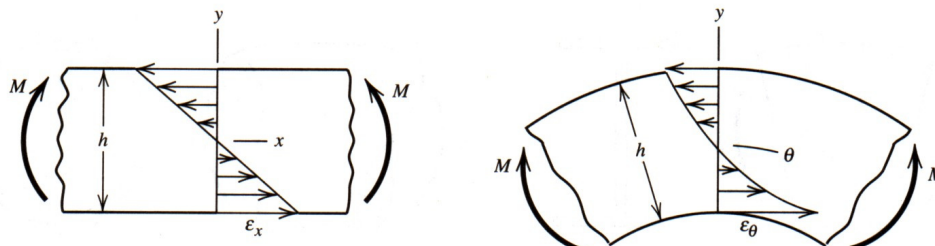
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2. A. Modeling Error

- To do a proper FE analysis, the analyst must understand how the structure is *likely* to behave and how elements are *able* to behave.
- E.g., if the analyst knows the displacement varies linearly, 4-node quad. elements will work, but if they vary quadratically, 8-node quad. elements must be used.



Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

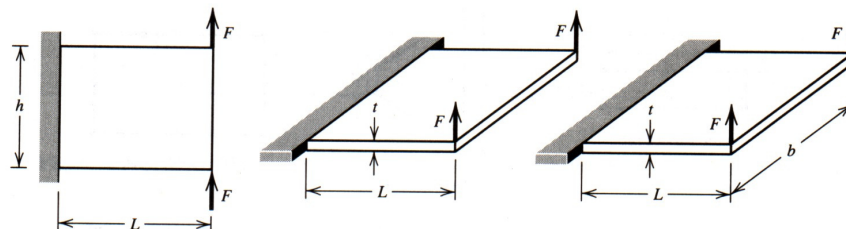
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Element Tests

- Use a *patch* test or *single element* test to determine how an element works under different circumstances.
- Study different states of stress and strain.



Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

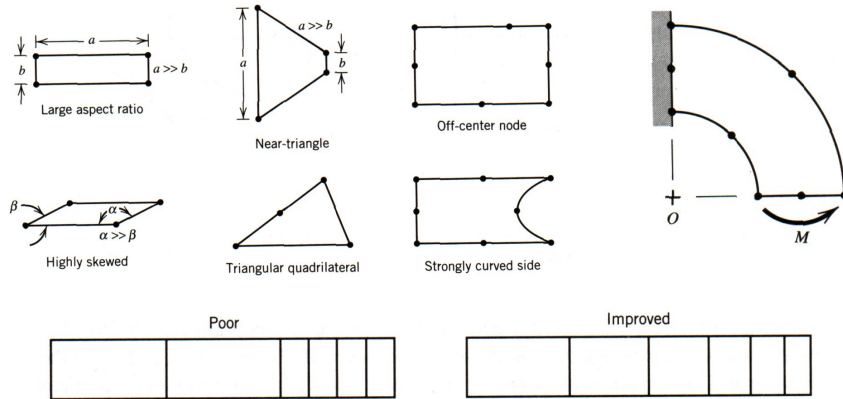
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Element Tests

- Study the effects of element distortions and changes in element size.



Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

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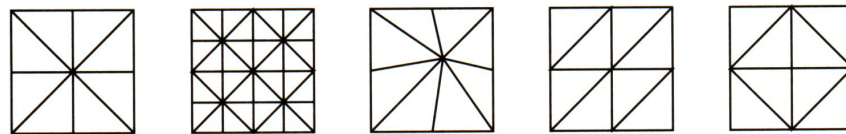


Test Cases

- Established test cases from:
 - research literature
 - National Agency for Finite Element Methods and Standards
 - software documentation

can be used to check the accuracy of elements and models.

- “Pilot studies” can be used to check software capabilities.



Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

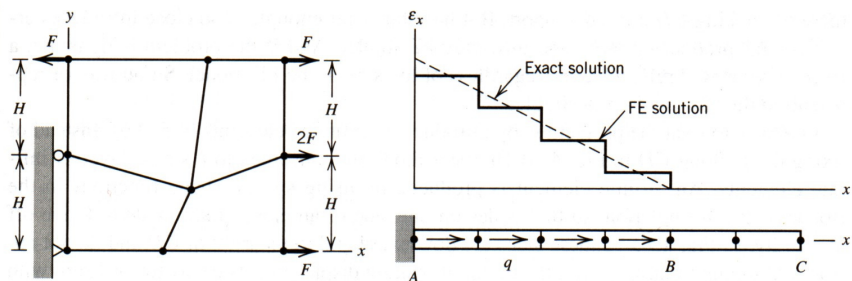
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2. B. Discretization Error

- If a mesh is repeatedly refined, will the results converge to a solution?
- Yes, if the elements used pass the “patch” test.



Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

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Convergence Requirements

- In a patch test, the FE model must have:
 - A simple arrangement of elements with one internal node
 - Supports sufficient to stop rigid body motion
 - Work equivalent loads consistent with a constant state of stress (and strain)
- To pass the test, the results must exactly represent the correct constant stress (and strain), within numerical error.

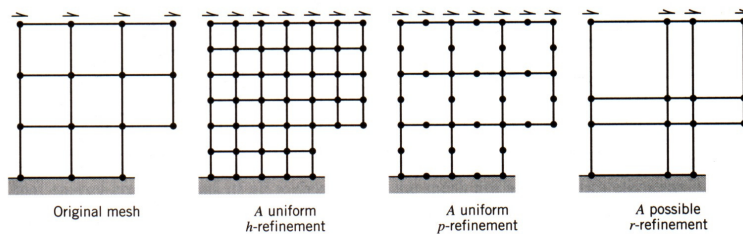
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Mesh Refinement

- There are three ways to refine a mesh:
 1. h -refinement (changing the element size)
 2. p -refinement (changing to elements with higher order polynomial interpolations)
 3. r -refinement (moving nodes)



Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

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Mesh Refinement

- A combination of these methods can also be used.
- The mesh should be refined until convergence is achieved (i.e., the results change very little from the previous refinement).
- Some software automates the refinement process (**adaptive meshing**).

Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

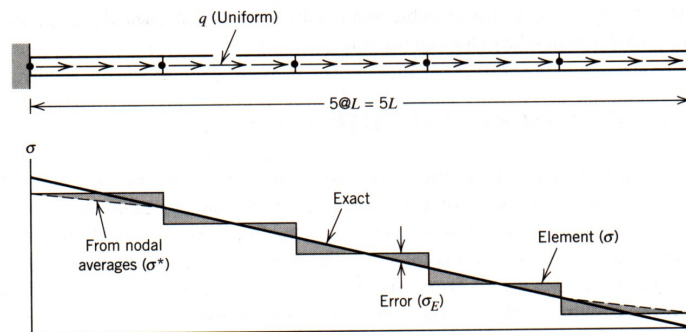
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Error Measures

One approach to error estimation is to assume that the nodal averaged stress (σ^*) is correct and the error (σ_E) is given at every point by the difference from the element stress (σ).



Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

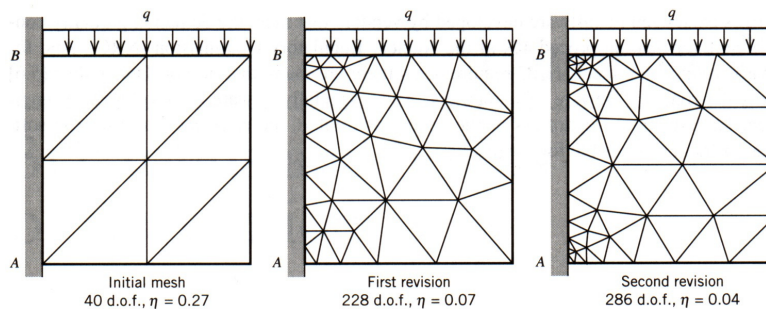
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Error Measures and Adaptivity

- An Automated Adaptive Solution proceeds by refining the mesh, in elements where the error is large, until the maximum error is below some limit.



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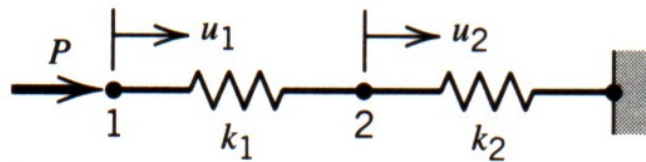
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2. C. Numerical Error

- Rounding errors will accumulate (more so in large DOF models)
- Adding very small numbers to big numbers is even more problematic (i.e. in “Stiff Systems”)



$$\mathbf{KD} = \mathbf{R} \quad \text{is} \quad \begin{bmatrix} k_1 & -k_1 \\ -k_1 & k_1 + k_2 \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} P \\ 0 \end{Bmatrix}$$

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Numerical Error – “Stiff” Systems

- If $k_1 \gg k_2$,

- If $k_2 \gg k_1$,

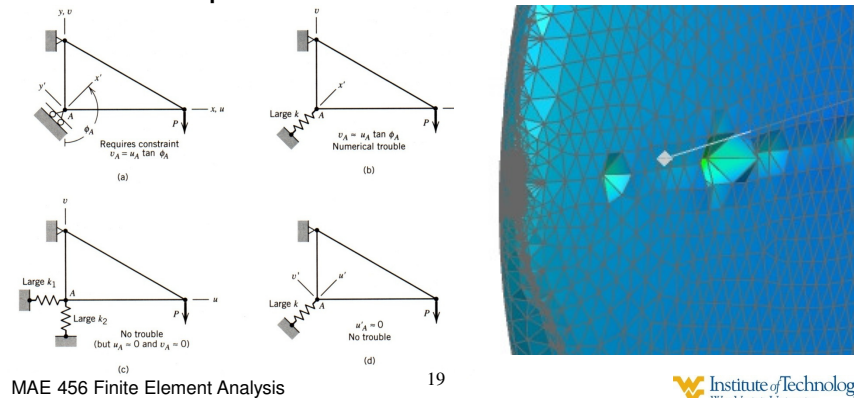
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Susceptibility to Ill-Conditioning

- Large cross-coupling stiffness coefficients will cause problems
- Having membrane stiffness \gg bending stiffness will cause problems.

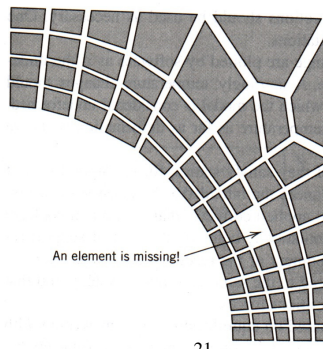


3. Checking the Model (before solving)

- Checking done automatically by software
 - Model has mesh and boundary conditions are applied.
 - All mesh and boundary condition properties have been provided.
 - Element aspect ratios and corner angles too small or too large.
 - Element is too warped.
 - Poisson's ratio too large.
 - Curved shell element spans too great an arc.
- Specific checks that can be requested
 - **Coincident** nodes (Are they supposed to be one node?)

Checking the Model (before solving)

- Checking done by Analyst
 - Everything meshed properly?
 - All required loads/support conditions applied?
 - Double-check material/shell/beam properties



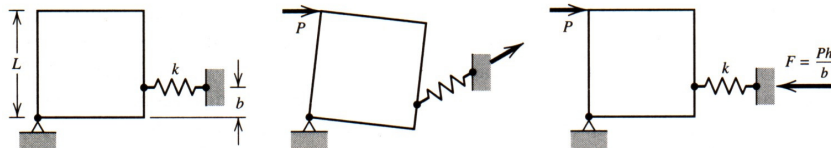
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Image from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.
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Checking the Results (after solving)

- Results should be checked so that:
 - **Deflections** obey intended **support conditions**.
 - Deflections are symmetric in a symmetric problem.
 - Where a gap closes the parts **do not overlap**.
 - **Support reactions** agree with static calculations.
 - There are no large displacements that cause **force directions to change** (use a nonlinear analysis in this case).



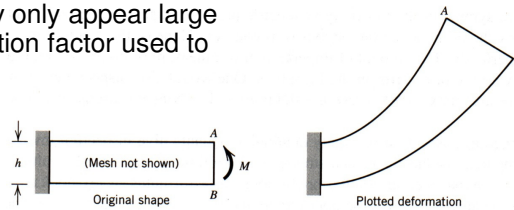
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Checking the Results

- Note that deflections may only appear large because of the exaggeration factor used to display the deflections.



Images from R. Cook, et al. *Concepts and Applications of Finite Element Analysis*, 1996.

- Stresses should be checked that:
 - Stress contours are normal to planes of symmetry
 - One of the principle stresses should be zero at an unloaded boundary or equal to $-p$ if there is a pressure p loading condition.

Checking the Results

- When checking stresses note that:
 - Unaveraged stresses should be checked.
 - Confirm that the displayed stress is the one you want to look at (i.e., principle stress vs. shear stress vs. von Mises stress, etc.)
 - Stresses may be in local or global coordinates
 - Stresses may be for the **upper, lower or mid-surface** of beam and shell elements.