Completeness

William Shoaff

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Reductions

We want a concepts that defines *at least as hard*, in that if we could solve problem A we could solve problem B, so A is at least as hard as problem B. This is the concept of *reduction*. So far we have used computable reductions: ones that could be implemented by some terminating Turing machine. Now we want to limit the resources used in a reduction. That is, we need to consider the efficiency of the reduction.

Polynomial time bounded reductions We say language L_1 reduces to language L_2 if there is a function

$$R: \Sigma_1 \to \Sigma_2$$

that is computable on a deterministic Turing machine in time $O(n^k)$ and $w \in L_1$ if and only if $R(w) \in L_2$.

Logarithmic space bounded reductions We say language L_1 reduces to language L_2 if there is a function

$$R: \Sigma_1 \to \Sigma_2$$

that is computable on a deterministic Turing machine in space $O(\log n)$ and $w \in L_1$ if and only if

$$R(w) \in L_2$$
.

Note that logarithmic space reductions imply polynomial time reductions. There are at most $O(nc^{\log n})$

configurations on input wwhere |w|=n. Since the machine is deterministic, no configuration can repeat. Thus the computation has length at most $O(n^k)$ for some k.

See examples of reductions in the text [1].

HAMILTON PATH can be reduced to SAT: Given a graph *G* we construct a Boolean expression R(G) such that *G* has a Hamilton path if and only if R(G) is satisfiable.. Suppose *G* has *n* vertices: 1, 2, ..., *n*; R(G) will have n^2 variables

$$x_{ij}, 1 \leq i, j \leq n$$

where x_{ij} will represent that ``node *j* is the *i* node of a Hamilton path'' (which may be true or false). R(G) is made of clauses:

The first series of clauses is true when each node *j* in the graph lies on a Hamilton path:

$$(x_{1j} \lor x_{2j} \lor \cdots \lor x_{nj}), \quad j = 1, \dots, n$$

node *j* is either the first, second, ...*n*th node on such a path.

The second series of clauses is true when node *j* is not both the *i*th and *k*th node on such a path:

$$(\neg x_{ij} \lor \neg x_{kj}), \quad j = 1, \dots, n, \quad i \neq k$$

Next some vertex must be the *i*th node on the path:

$$(x_{i1} \lor x_{i2} \lor \cdots \lor x_{in}), \quad i = 1, \dots, n$$

And no two vertices can be the *i*th node on the path:

$$(\neg x_{ij} \lor \neg x_{ik}), \quad i = 1, \dots, n, \quad j \neq k$$

Finally, vertex *j* can come right after *i* only if (i, j) is an edge in *G*, so for each pair (i, j) that is not an edge in *G* we include:

$$(\neg x_{ki} \lor \neg x_{k+1,j}), \quad k = 1, \dots, n-1.$$

The expression R(G) is the conjunction of all these clauses.

To show that *R* is a reduction from HAMILTON PATH to SAT we must show: (1) for any graph *G*, expression R(G) has a satisfying truth assignment if and only if *G* has a Hamilton path, and (2) *R* can be computed in logarithmic space.

Suppose R(G) has a truth assignment T.

For each *j* there is a unique *i* such that $T(x_{ij}) =$ **true**otherwise the clauses

$$(\neg x_{ij} \lor \neg x_{kj}), \quad \text{and}(x_{1j} \lor x_{2j} \lor \cdots \lor x_{nj})$$

cannot all be satisfied. Similarly for each *i* there is a unique *j* such that $T(x_{ij})$ =true, or not all of

$$(\neg x_{ij} \lor \neg x_{ik}), \quad \text{and}(x_{i1} \lor x_{i2} \lor \cdots \lor x_{in})$$

can all be satisfied.

Hence T can be thought of as a permutation of the vertices of $G \pi(i) = j$ where $T(x_{ij})$ =true

Moreover, the clauses

$$(\neg x_{ki} \lor \neg x_{k+1,j})$$

where (i,j) is not an edge guarantee that for all k $(\pi(i), \pi(j))$ is an edge of G and thus

$$(\pi(1),\pi(2),\ldots\pi(n))$$

is a Hamilton path.

Conversely, if G has a Hamilton path

$$(\pi(1), \pi(2), \dots, \pi(n))$$

then the truth assignment $T(x_{ij}) = \text{true if } \pi(i) = j$ and $T(x_{ij}) = \text{false if } \pi(i) \neq j$ satisfies the clauses of G.

Now let's show we use only logarithmic space in the computation of R. Given G a Turing machine M outputs R(G) as follows:

1.

Write *n* the number of vertices in *G* (in binary [logarithmic space])

2.

Generate on the output tape the clauses that do not depend on G (the first four sets of clauses) Here, M just needs three counters for i, j, and k

3.

For the remaining clauses describing edges M generates one by one all clauses of the form:

$$(\neg x_{ki} \lor \neg x_{k+1,j}), \quad k = 1, \dots, n-1$$

M then looks at its input to see if (i,j) is an edge of *G* and if not outputs the Boolean clause. Again the counters i, j, and k are sufficient to complete this computation.

REACHABILITY can be reduced to CIRCUIT VALUE.

Given a graph G construct a variable free circuit R(G) with output **true** if and only if there is a path from node 1 to node n in G.

Gates of R(G) are of the form

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1.
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 g_{ijk} where $1 \leq i, j \leq n$ and $0 \leq k \leq n$

2.

 h_{ijk} where $1 \leq i, j, k \leq n$

 g_{ijk} will output **true** if and only if there is a path in G from i to j not using any intermediate node bigger than k.

 h_{ijk} will output **true** if and only if there is a path in G from i to j not using any intermediate node bigger than k, but using k as an intermediate node.

For k=0, g_{ij0} are input gates that are **true** if i=j or (i,j) is an edge of G and **false** otherwise.

For $k = 1, \dots, n$, h_{ijk} is an AND gate with predecessors $g_{i,k,k-1}$ and $g_{k,j,k-1}$

For $k = 1, \dots, n$, g_{ijk} is an **OR** gate with predecessors $g_{i,j,k-1}$ and $h_{i,j,k}$

Finally g_{1nn} is the output gate.

We will show by induction on k that g_{ijk} will output **true** if and only if there is a path in G from i to j not using any intermediate node bigger than k and h_{ijk} will output **true** if and only if there is a path in G from i to j not using any intermediate node bigger than k, but using k as an intermediate node.

For k=0, g_{ij0} will output **true** if and only if there is a an path (edge) from *i* to *j* (this includes the empty path from *i* to *i* when j=i).

Suppose the outputs of g and h gates are as described up to k-1 for some $k \ge 1$. Since

 $h_{ijk} = (g_{i,k,k-1} \land g_{k,j,k-1}) h_{ijk}$ will output **true** if and only if $g_{i,k,k-1}$ and $g_{k,j,k-1}$ are **true**.

And since $g_{ijk} = (g_{i,j,k-1} \vee h_{i,j,k}) g_{ijk}$ will output **true** if and only if one of $g_{i,j,k-1}$ or $h_{i,j,k}$ is **true**.

In particular, g_{1nn} will be true if and only if there is a path from 1 to n in G.

Finally, R(G) can be computed in logarithmic space by going over all vertices i, j and k and output the appropriate edges and gate types for the variables. (See the Floyd-Warshall algorithm from a text on algorithms).

Completeness

Definition Let C be a complexity class, and let $L \in C$. The language L is C-complete if any language

 $L' \in C$ can be reduced to L.

It is not clear that complete problems even exist. But they are a central concept, they capture the difficulty of a class (they are at least as hard as every other problem in the class). Being able to solve a complete problem implies we can solve (in theory at least) any problem in that class.

The existence of important, natural problems that are complete for a class tend to make a class significant; absence of such problems indicate the class may be artificial.

The most common use of completeness is to derive a *negative complexity result*: a complete problem *P* for class *C* is the least likely to belong to a subclass $C' \subseteq C$, provided the class *C* is closed under reductions.

Definition: A class C' is closed under reductions if whenever L is reducible to L' and $L' \in C'$ then $L \in C'$.

Proposition: P, NP, coNP, L, NL, PSPACE, EXP are all closed under reductions.

For example, consider \mathbb{P} and suppose L is reducible to $L' \in \mathbb{P}$, using logarithmic space reduction R. To

decide: $w \in L$ construct the reduction R(w) (in logarithmic space, hence polynomial time) and then decide if

 $R(w) \in L$ using the Turing machine M that decides L in polynomial time.

Complete problems are valuable since if we can show an NP complete problem is in P then P = NP (and so on for other complexity classes).

Theorem CIRCUIT VALUE is **P** complete.

AND, OR, and NOT can be used in an instance CIRCUIT VALUE. If we exclude NOT gates the problem remains \mathbb{P} complete. Such (monotone) circuits are less expressive than general circuits, but by appling De Morgan's laws we can move all NOTs to the input and then change *frue* to false and vice versa.

Cook's Theorem SAT is **№** complete.

Theorem Let L be complete for class \mathbb{C} . If $L' \in \mathbb{C}$ and L reduces to L', then L' is complete for class \mathbb{C} .

Let *L*" be any language in class \mathbb{C} . Since *L* is \mathbb{C} -complete there is a reduction *R*" from *L*" to *L*. Let *R*' be the reduction from *L* to *L*'. Then, since the composition of reductions is a reduction, $\mathbf{R} = \mathbf{R}^{tt} \circ \mathbf{R}^{t}$ is a reduction from *L*" to *L*'

Bibliography

1

C. H. PAPADIMITRIOU, Computational Complexity, Addison-Wesley, 1994.

William Shoaff 2001-03-14