

# Relations between Complexity Classes

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The Reachability Method

# Outline

- 1 The Reachability Method
  - Some basic theorems
  - Non-deterministic Space

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# Some basic theorems

## Theorem

Suppose that  $f(n)$  is a proper complexity function. Then:

- (i)  $\text{SPACE}(f(n)) \subseteq \text{NSPACE}(f(n))$  and  $\text{TIME}(f(n)) \subseteq \text{NTIME}(f(n))$ .
- (ii)  $\text{NTIME}(f(n)) \subseteq \text{SPACE}(f(n))$ .
- (iii)  $\text{NSPACE}(f(n)) \subseteq \text{TIME}(k^{\log n + f(n)})$ .

## Proof.

(i) and (ii) are trivial. For (iii), assume that we are given a  $k$ -string NDTM  $M$  with input and output that decides  $L$  in space  $f(n)$ . A configuration of  $M$  can be described as  $(q, i, w_2, u_2, \dots, w_{k-1}, u_{k-1})$ , where  $0 \leq i \leq n$  marks a position in the input string. Total number of configurations =  $|K| \times (n+1) \times |\Sigma|^{(2k-2)f(n)} = nc_1^{f(n)} = c_1^{f(n) + \log n}$ . Create the configuration graph  $G(M, x)$  on input  $x$ ; vertices are configurations and there exists an edge from the vertex representing  $C_1$  to the vertex representing  $C_2$  if and only if  $C_1 \rightarrow_M C_2$ .  $x \in L$  if and only if there is a path from  $C_0 = (s, 0, \triangleright, \epsilon, \dots, \epsilon)$  to some  $C = (\text{"yes"}, \dots)$ .  $\square$

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But now the problem is REACHABILITY in a graph with  $c_1^{f(n)+\log n}$  nodes. Can be accomplished in  $c_2 \cdot (c_1^{f(n)+\log n})^2 = c_2 \cdot c_1^{2 \cdot (f(n)+\log n)} = k^{f(n)+\log n}$  time using a standard reachability algorithm.  $\square$

## Corollary

$L \subseteq NL \subseteq P \subseteq NP \subseteq PSPACE.$

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REACHABILITY  $\in$  **SPACE**( $\log^2 n$ ).

## Proof.

Let  $G$  be a graph with  $n$  nodes and  $x, y \in G$ .  $\text{PATH}(x, y, i)$  is **true**, if there is a path of length at most  $2^i$  from  $x$  to  $y$  in  $G$ . REACHABILITY coincides with checking whether  $\text{PATH}(x, y, \lceil \log n \rceil)$  is **true**.

We design a 2-string Turing machine with input and output. The adjacency matrix of  $G$  is stored on the input string. The first string contains several triples with  $(x, y, i)$  denoting the first triple. The second string will be used as scratch space.

Two cases to consider

- (i)  $i = 0$  - Check if  $(x, y)$  is an edge!
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for all nodes  $z \in G$ , test whether  $\text{PATH}(x, z, i - 1) \wedge \text{PATH}(z, y, i - 1)$ .

Implementing the recursion in a space efficient manner - Generate all vertices  $z$ , one after the other reusing space. Interpret positive and negative answers to  $\text{PATH}(x, z, i - 1)$  correctly. Stack size is at most  $\log n$  triples of size  $3 \log n$  each. Thus, total space used is  $O(\log^2 n)$ . □

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# Savitch's theorem (contd.)

## Corollary

$\text{NSPACE}^{f(n)} \subseteq \text{SPACE}((f(n))^2)$  for any proper complexity function  $f(n) \geq \log n$ .

## Proof.

Given an  $f(n)$ -space bounded NDTM, simply run the previous algorithm on the configuration graph  $G(M, x)$ , where  $|x| = n$ . Since  $G(M, |x|)$  has at most  $c^{f(n)}$  nodes,  $O((f(n))^2)$  space suffices.  $\square$

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# Counting the number of reachable nodes

## Definition

A NDTM  $M$  is said to compute a function  $f$  from strings to strings, if all “yes” leaves have the output  $f(x)$ .

## Theorem (Immerman-Szelepcényi Theorem)

*Given a graph  $G$  with  $n$  nodes, and a node  $x \in G$ , the number of nodes reachable from  $x$  in  $G$  can be computed by a NDTM in space  $\log n$ .*

## Proof.

Let  $S(i)$  denote the set of vertices that can be reached from  $x$  using paths of length at most  $i$ . We are interested in  $|S(n-1)|$ .

*loop<sub>1</sub>* :  $|S(0)| := 1$ ; **for**  $i = 1, 2, \dots, n-1$ : compute  $|S(i)|$  from  $|S(i-1)|$ . □

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## Proof.

*loop*<sub>2</sub> :  $l := 0$ ; **for** each node  $u = 1, 2, \dots, n$ : if  $u \in S(k)$ , then  $l := l + 1$ .

How to decide whether  $u \in S(k)$ ?

*loop*<sub>3</sub>:  $m := 0$ ; *reply* = **false**; **for** each node  $v = 1, 2, \dots, n$  **repeat**:  
if  $v \in S(k-1)$  then  $m := m + 1$ . Further, if  $G(v, u)$ , then *reply* = **true**.  
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*loop*<sub>2</sub> :  $l := 0$ ; **for** each node  $u = 1, 2, \dots, n$ : if  $u \in S(k)$ , then  $l := l + 1$ .  
How to decide whether  $u \in S(k)$ ?

*loop*<sub>3</sub>:  $m := 0$ ; **reply** = **false**; **for** each node  $v = 1, 2, \dots, n$  **repeat**:  
if  $v \in S(k - 1)$  then  $m := m + 1$ . Further, if  $G(v, u)$ , then **reply** = **true**.  
if at end,  $m < |S(k - 1)|$ , then "no", else return **reply**.  
How to check if  $v \in S(k - 1)$ ?

Simple! Start at node  $x$  and guess  $k - 1$  nodes.

*loop*<sub>4</sub>:  $w_0 := x$ . **for**  $p = 1, 2, \dots, k - 1$ :  
guess a node  $w_p$  and check that  $G(w_{p-1}, w_p)$ . (If not, return "no").  
if  $w_{k-1} = v$ , then report  $v \in S_{k-1}$ , else "no".



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# Consequences of counting theorem

## Corollary

If  $f(n) \geq \log n$  is a proper complexity function, then  $\mathbf{NSPACE}(f(n)) = \mathbf{coNSPACE}(f(n))$ .

## Proof.

Let  $L \in \mathbf{NSPACE}(f(n))$ , i.e.,  $L$  is decided by a NDTM  $M$  that is  $f(n)$ -space bounded. We construct an NDTM  $\bar{M}$  to decide  $\bar{L}$  as follows: Simply run the algorithm of the Immerman-Szelepcsenyi theorem on  $G(M, x)$ ! If  $\bar{M}$  discovers an accepting configuration in any  $S(k)$ ,  $k = 0, 1, \dots, n-1$ , then it halts and rejects. The other possibility is that  $|S(n-1)|$  is computed and no accepting configuration is discovered, in which case  $\bar{M}$  accepts.

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