

Dynamic Tables

- Why?
- $\alpha(T)$, load factor
- Array of slots
- Table expansion
 - size of array slots is the previous one
 - load factor $\geq \frac{1}{2}$
 - create new table, move all elements, free old table

→ n Table-maint operations at any point in time
empty table

$C_i \in O(n^i)$ in worst case
⇒ $O(n^i \log n)$

$$C_i = \begin{cases} 0, & \text{if } i-1 \geq \log n \\ 1, & \text{otherwise} \end{cases}$$

$$\sum_{i=1}^n C_i \leq n + \sum_{j=0}^{\log n} 2^j$$

$$< n + 2n$$

$$= 3n$$

Why $3n$. 1 for insertion, 1 for moving,
1 for moving and for check.

Rekabel my No.

$$\phi(i) = 2 \cdot T_{num} - T_{size}$$

Immediately after an expansion: $T_{num} = T_{size}/2$

$$\phi(i) = 0$$

Immediately before an expansion

$$\phi(i) = T_{num}$$

$$T_{num} \geq \frac{T_{size}}{2}$$

$$\Rightarrow \phi(i) \geq 0$$

$$num_0 = 0, \quad size_0 = 0, \quad \phi_0 = 0$$

ϕ_i does not trigger expansion

$$c_i^* = c_0 + \phi_i - \phi_{i-1}$$

$$= 1 + (2 \cdot num_{i-1} - size_{i-1}) - (2 \cdot num_{i-2} - size_{i-2})$$

$$= 3 \cdot 0$$

does trigger expansion $size_i = 2 \cdot size_{i-1}$

$$c_i^* = c_0 + \phi_i - \phi_{i-1}$$

$$size_{i-1} = num_{i-1}$$

$$= num_i - (2 \cdot num_{i-1} - size_{i-1})$$

$$= num_i - 1$$

$$= 3 \quad \text{size}_i = 2 \cdot (num_{i-1} - 1)$$

Table expansion and contraction

→ why does simple halving & doubling not work?

$$\phi(i) = \begin{cases} 2 \cdot T_{\text{num}} - T_{\text{size}}, & \text{if } \alpha(i) \geq 1/2 \\ \frac{T_{\text{size}} - T_{\text{num}}}{2} & \text{if } \alpha(i) < 1/2 \end{cases}$$

implies $\Phi(T) = T.num$, and thus the potential can pay for a contraction if an item is deleted.

To analyze a sequence of n TABLE-INSERT and TABLE-DELETE operations, we let c_i denote the actual cost of the i th operation, \hat{c}_i denote its amortized cost with respect to Φ , num_i denote the number of items stored in the table after the i th operation, $size_i$ denote the total size of the table after the i th operation, α_i denote the load factor of the table after the i th operation, and Φ_i denote the potential after the i th operation. Initially, $num_0 = 0$, $size_0 = 0$, $\alpha_0 = 1$, and $\Phi_0 = 0$.

We start with the case in which the i th operation is TABLE-INSERT. The analysis is identical to that for table expansion in Section 17.4.1 if $\alpha_{i-1} \geq 1/2$. Whether the table expands or not, the amortized cost \hat{c}_i of the operation is at most 3. If $\alpha_{i-1} < 1/2$, the table cannot expand as a result of the operation, since the table expands only when $\alpha_{i-1} = 1$. If $\alpha_i < 1/2$ as well, then the amortized cost of the i th operation is

$$\begin{aligned}\hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} \\ &= 1 + (size_i/2 - num_i) - (size_{i-1}/2 - num_{i-1}) \\ &= 1 + (size_i/2 - num_i) - (size_i/2 - (num_i - 1)) \\ &= 0.\end{aligned}$$

If $\alpha_{i-1} < 1/2$ but $\alpha_i \geq 1/2$, then

$$\begin{aligned}\hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} \\ &= 1 + (2 \cdot num_i - size_i) - (size_{i-1}/2 - num_{i-1}) \\ &= 1 + (2(num_{i-1} + 1) - size_{i-1}) - (size_{i-1}/2 - num_{i-1}) \\ &= 3 \cdot num_{i-1} - \frac{3}{2}size_{i-1} + 3 \\ &= 3\alpha_{i-1}size_{i-1} - \frac{3}{2}size_{i-1} + 3 \\ &< \frac{3}{2}size_{i-1} - \frac{3}{2}size_{i-1} + 3 \\ &= 3.\end{aligned}$$

Thus, the amortized cost of a TABLE-INSERT operation is at most 3.

We now turn to the case in which the i th operation is TABLE-DELETE. In this case, $num_i = num_{i-1} - 1$. If $\alpha_{i-1} < 1/2$, then we must consider whether the operation causes the table to contract. If it does not, then $size_i = size_{i-1}$ and the amortized cost of the operation is

$$\begin{aligned}\hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} \\ &= 1 + (size_i/2 - num_i) - (size_{i-1}/2 - num_{i-1}) \\ &= 1 + (size_i/2 - num_i) - (size_i/2 - (num_i + 1))\end{aligned}$$

If $\alpha_{i-1} < 1/2$ and the i th operation ~~does trigger~~ a contraction, then the actual cost of the operation is $c_i = \text{num}_i + 1$, since we delete one item and move num_i items. We have $\text{size}_i/2 = \text{size}_{i-1}/4 = \text{num}_{i-1} = \text{num}_i + 1$, and the amortized cost of the operation is

$$\begin{aligned}\hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} \\ &= (\text{num}_i + 1) + (\text{size}_i/2 - \text{num}_i) - (\text{size}_{i-1}/2 - \text{num}_{i-1}) \\ &= (\text{num}_i + 1) + ((\text{num}_i + 1) - \text{num}_i) - ((2 \cdot \text{num}_i + 2) - (\text{num}_i + 1)) \\ &= 1.\end{aligned}$$

When the i th operation is a TABLE-DELETE and $\alpha_{i-1} \geq 1/2$, the amortized cost is also bounded above by a constant. We leave the analysis as Exercise 17.4-2.

In summary, since the amortized cost of each operation is bounded above by a constant, the actual time for any sequence of n operations on a dynamic table is $O(n)$.

Exercises

17.4-1

Suppose that we wish to implement a dynamic, open-address hash table. Why might we consider the table to be full when its load factor reaches some value α that is strictly less than 1? Describe briefly how to make insertion into a dynamic, open-address hash table run in such a way that the expected value of the amortized cost per insertion is $O(1)$. Why is the expected value of the actual cost per insertion not necessarily $O(1)$ for all insertions?

17.4-2

Show that if $\alpha_{i-1} \geq 1/2$ and the i th operation on a dynamic table is TABLE-DELETE, then the amortized cost of the operation with respect to the potential function (17.6) is bounded above by a constant.

17.4-3

Suppose that instead of contracting a table by halving its size when its load factor drops below $1/4$, we contract it by multiplying its size by $2/3$ when its load factor drops below $1/3$. Using the potential function

$$\Phi(T) = |2 \cdot T.\text{num} - T.\text{size}|,$$

show that the amortized cost of a TABLE-DELETE that uses this strategy is bounded above by a constant.