Monte Carlo Method

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- Definition
- Example

Outline



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- Example



- Markov Chain Monte Carlo Method
 - Introduction
 - Metropolis Algorithm



Approximate Sampling to Approximate Counting Definition

Example



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Definition Example

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A sampling algorithm is a fully polynomial almost uniform sample (*FPAUS*) for a problem if, given an input *x* and a parameter $\varepsilon > 0$, it generates an ε - uniform sample of $\Omega(x)$ and runs in time that is polynomial in $\ln \varepsilon^{-1}$ and the size of the input x.



Approximate Sampling to Approximate Counting

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Example

Meghana Randomized Algorithms

Example

FPAUS for independent sets.

Example

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Question

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Input : Graph G = (V, E) and parameter ε . Sample space : All independent sets in *G*. Output : ε -uniform sample of the independent sets. Goal : To show that, given an FPAUS for independent sets, we can construct an FPRAS for counting the number of independent sets.

Continued

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Let $\Omega(G_i)$ denote set of independent sets in G_i . The number of independent sets in *G* can be expressed as,

$$|\Omega(G)| = \frac{|\Omega(G_m)|}{|\Omega(G_{m-1})|} \times \frac{|\Omega(G_{m-1})|}{|\Omega(G_{m-2})|} \times \frac{|\Omega(G_{m-2})|}{|\Omega(G_{m-3})|} \times \cdots \times \frac{|\Omega(G_1)|}{|\Omega(G_0)|} \times |\Omega(G_0)|.$$

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$$\mathsf{R}=\prod_{i=1}^m\frac{\tilde{r}_i}{r_i}.$$

To have an (ε, δ) -approximation, we want $P(|R-1| \le \varepsilon) \ge 1 - \delta$.

Lemmas

Lemma

Suppose that for all *i*, $1 \le i \le m$, \tilde{r}_i is an $(\frac{\varepsilon}{2 \cdot m}, \frac{\delta}{m})$ -approximation for r_i . Then,

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Definition

Proof

For each $1 \le i \le m$, we have

$$\begin{aligned} & \mathcal{P}(|\tilde{r}_i - r_i| \leq \frac{\varepsilon}{2 \cdot m} \cdot r_i) \geq 1 - \frac{\delta}{m} \\ & \mathcal{P}(|\tilde{r}_i - r_i| > \frac{\varepsilon}{2 \cdot m} \cdot r_i) < \frac{\delta}{m} \end{aligned}$$

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By union bound, the probability that $|\tilde{r}_i - r_i| > (\frac{\varepsilon}{2 \cdot m}) \cdot r_i$ for any *i* is at most δ ; Therefore $|\tilde{r}_i - r_i| \leq (\frac{\varepsilon}{2 \cdot m} \cdot r_i)$ for all *i* with probability at least $1 - \delta$. Equivalently,

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$$1 - \frac{\varepsilon}{2 \cdot m} \leq \frac{\tilde{r}_i}{r_i} \leq 1 + \frac{\varepsilon}{2 \cdot m}$$

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We need a method for obtaining an $(\frac{\varepsilon}{2 \cdot m}, \frac{\delta}{m})$ - approximation for the r_i . We estimate each of these ratios by a Monte Carlo algorithm that uses *FPAUS* for sampling independent sets.

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To estimate r_i , we sample independent sets in G_{i-1} and compute the fraction of these sets that are also independent sets in G_i , as shown in the following algorithm.

Algorithm

Estimating r _i :
Input: Graphs $G_{i-1} = (V, E_{i-1})$ and $G_i = (V, E_i)$. Output: $\tilde{r}_i =$ an approximation of r_i .
1: $X \leftarrow 0$
2: repeat
3: Generate an $(\frac{\varepsilon}{6.m})$ – uniform sample from $\Omega(G_{i-1})$.
4: If the sample is an independent set in G_i , let $X \leftarrow X + 1$
5: until $M = \left[1296 m^2 \varepsilon^{-2} \ln\left(\frac{2 \cdot m}{\delta}\right) \right]$ independent trials
6: return $\tilde{r_i} \leftarrow \frac{X}{M}$

Algorithm 2.1: Estimating r_i

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When $m \ge 1$ and $0 < \varepsilon \le 1$, the procedure for estimating r_i yields an $(\frac{\varepsilon}{2 \cdot m}, \frac{\delta}{m})$ -approximation for r_i .

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$$r_i = \frac{|\Omega(G_i)|}{|\Omega(G_{i-1})|} = \frac{|\Omega(G_i)|}{|\Omega(G_i)| + |\Omega(G_{i-1}) \setminus \Omega(G_i)|} \ge \frac{1}{2}.$$

continued

Consider *M* samples and let X_k be

$$X_k = \begin{cases} 1 & \text{if the } k^{\text{th}} \text{ sample is in } \Omega(G_i) \\ 0 & \text{otherwise} \end{cases}$$

continued

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Definition

Since our samples are generated by an $(\frac{\varepsilon}{6 \cdot m})$ - uniform sampler, by our previous definition each X_i must satisfy,

$$|P(X_k=1)-\frac{|\Omega(G_i)|}{|\Omega(G_{i-1})|}|\leq \frac{\varepsilon}{6\cdot m}.$$

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Since X_k are indicator random variables and further by linearity of expectations, we get

$$\mathbf{E}[\tilde{r}_i] - r_i| = |\mathbf{E}[\frac{\sum_{i=1}^M X_k}{M}] - \frac{|\Omega(G_i)|}{|\Omega(G_{i-1})|}| \le \frac{\varepsilon}{6 \cdot m}$$

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Lemma is completed by combining

- (a) $\mathbf{E}[\tilde{r}_i]$ is close to r_i and
- (b) \tilde{r}_i will be close to $\mathbf{E}[\tilde{r}_i]$ for a sufficiently large number of samples .

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Since our samples are generated by an $(\frac{c}{6 \cdot m})$ - uniform sampler, by our previous definition each X_i must satisfy,

$$|P(X_k = 1) - \frac{|\Omega(G_i)|}{|\Omega(G_{i-1})|}| \leq \frac{\varepsilon}{6 \cdot m}.$$

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(b) \tilde{r}_i will be close to $\mathbf{E}[\tilde{r}_i]$ for a sufficiently large number of samples .

Using the above and $r_i \ge 1/2$ gives the desired $(\frac{\varepsilon}{2 \cdot m}, \frac{\delta}{m})$ - approximation.

Theorems

Theorem

Given a fully polynomial almost uniform sampler (*FPAUS*) for independent sets in any graph, we can construct a fully polynomial randomized approximation scheme (*FPRAS*) for the number of independent sets in a graph *G*.

Theorem

Given a fully polynomial almost uniform sampler (*FPAUS*) for independent sets in any graph with maximum degree at most Δ , we can construct a fully polynomial randomized approximation scheme (*FPRAS*) for the number of independent sets in a graph *G* with maximum degree at most Δ .

Outline



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• Metropolis Algorithm

Introduction

Definition

The Markov chain Monte Carlo (*MCMC*) method provides a very general approach to sampling from a desired probability distribution.

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The Markov chain Monte Carlo (*MCMC*) method provides a very general approach to sampling from a desired probability distribution.

Where MCMC is used

- (i) Data Mining and Machine Learning
- (ii) Bayesian methods
- (iii) Biological and generic research

ntroduction Metropolis Algorithm

Recall Markov chain

Questions

Meghana Randomized Algorithms

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Recall Markov chain

Questions

(i) Irreducible?

Introduction Metropolis Algorithm

Recall Markov chain

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Recall Markov chain

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Recall Markov chain

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- (ii) Aperiodic? A state is periodic if it can only return to itself after a fixed number of transitions greater than 1 (or multiple of a fixed number). A state that is not periodic is aperiodic. A Markov chain is aperiodic if all states of the chain are aperiodic.
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- (iii) Ergodic Markov chain? A state *i* is said to be ergodic if it is aperiodic and positive recurrent. If all states in an irreducible Markov chain are ergodic, then the chain is said to be ergodic.
- (iv) Stationary distribution? A stationary distribution of a Markov chain is a probability distribution $\bar{\pi}$ such that $\bar{\pi} = \bar{\pi} \cdot P$

Recall Markov chain continued

Theorem (for stationary distribution)

Consider a finite, irreducible, and ergodic Markov chain with transition matrix *P*. If there are nonnegative numbers $\bar{\pi} = (\pi_0, ... \pi_n)$ such that $\sum_{i=0}^n \pi_i = 1$ and if, for any pair of states *i*, *j*,

$$\pi_i \cdot P_{i,j} = \pi_j \cdot P_{j,i},$$

then π_i is the stationary distribution corresponding to P.

Recall Markov chain continued

Theorem (for stationary distribution)

Consider a finite, irreducible, and ergodic Markov chain with transition matrix *P*. If there are nonnegative numbers $\bar{\pi} = (\pi_0, ... \pi_n)$ such that $\sum_{i=0}^n \pi_i = 1$ and if, for any pair of states *i*, *j*,

$$\pi_i \cdot P_{i,j} = \pi_j \cdot P_{j,i},$$

then π_i is the stationary distribution corresponding to P.

Theorem

A random walk on G converges to a stationary distribution $\bar{\pi}$, where

$$\pi_{v}=\frac{d(v)}{2\cdot|E|}.$$

In a stationary distribution of a random walk, the probability of a vertex is proportional to the degree of the vertex.

Approximate Sampling to Approximate Counting Markov Chain Monte Carlo Method Introduction Metropolis Algorithm

MCMC Continued

Basic Idea

Define an ergodic Markov chain whose set of states is the sample space and whose stationary distribution is the required sampling distribution.

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Similarly starting from X_r , $X_{2 \cdot r}$ can be used as a sample and so on.

Therefore the sequence of states $X_r, X_{2 \cdot r}, X_{3 \cdot r}, \ldots$ can be used as the almost

independent samples from the stationary distribution of the Markov chain.

Approximate Sampling to Approximate Counting Markov Chain Monte Carlo Method

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MCMC Continued

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For a finite state space Ω and neighborhood structure $\{N(X)|x \in \Omega\}$, let $N = \max_{x \in \Omega} |N(x)|$.

MCMC Continued

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If this chain is irreducible and aperiodic, then the stationary distribution is the uniform distribution.

Approximate Sampling to Approximate Counting Markov Chain Monte Carlo Method

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MCMC Continued

Proof

We show that chain is time reversible and apply Theorem (for stationary distribution).

Approximate Sampling to Approximate Counting Markov Chain Monte Carlo Method Introduction Metropolis Algorithm

MCMC Continued

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 $\implies \pi_{x} = \frac{1}{|\Omega|}$ is the stationary distribution.

Example

Example

Consider the following simple Markov chain, whose states are independent sets in a graph G = (V, E).

(1) X_0 is an arbitrary independent set in *G*.

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Outline



- Definition
- Example



- Introduction
- Metropolis Algorithm

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Metropolis Algorithm

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Metropolis Algorithm

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Notes

Assume we have designed an irreducible state space for a Markov chain. We want to construct Markov chain on this state space with a stationary distribution, $\pi_x = \frac{b(x)}{B}, \forall x \in \Omega$ we have b(x) > 0 such that $B = \sum_{x \in \Omega} b(x)$ is finite.

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Then, if this chain is irreducible and aperiodic, the stationary distribution is given by the probabilities π_x .

Proof

We show that chain is time reversible and apply Theorem (for stationary distribution).

Introduction Metropolis Algorithm

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We show that chain is time reversible and apply Theorem (for stationary distribution). For any $x \neq y$ if $\pi_x \leq \pi_y$ then $P_{x,y} = 1$ and $P_{y,x} = \frac{\pi_x}{\pi_y}$.

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ntroduction Metropolis Algorithm

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Choose a vertex v to add or delete with probability $\frac{1}{M}$; here M = |V|.

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Two-step approach

Choose a vertex v to add or delete with probability $\frac{1}{M}$; here M = |V|. This proposal is accepted with probability $min(1, \frac{\pi_y}{\pi_x})$, where x is current state and y is proposed state.

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Choose a vertex v to add or delete with probability $\frac{1}{M}$; here M = |V|. This proposal is accepted with probability $min(1, \frac{\pi_y}{\pi_x})$, where x is current state and y is proposed state.

(i) If chain adds a vertex, $\frac{\pi_y}{\pi_x}$ is λ

Example

Consider the following variation on previous Markov chain for independent sets in a graph G = (V, E).

- (1) X_0 is an arbitrary independent set in G.
- (2) To compute X_{i+1} :
 - (a) choose a vertex v uniformly at random from V,
 - (b) if $v \in X_i$, set $X_{i+1} = X_i \setminus \{v\}$ with probability min $(1, \frac{1}{\lambda})$,
 - (c) if $v \notin X_i$ and if adding v to X_i still gives an independent set, then put $X_{i+1} = X_i \cup \{v\}$ with probability min $(1, \lambda)$,
 - (d) otherwise, set $X_{i+1} = X_i$.

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- (i) If chain adds a vertex, $\frac{\pi_y}{\pi_x}$ is λ
- (ii) If chain deletes a vertex $\frac{\pi_y}{\pi_x}$ is $\frac{1}{\lambda}$ The transition probability $P_{x,y} = \frac{1}{M} \cdot \min(1, \frac{\pi_y}{\pi_x})$, so Lemma applies.

Notes

We dint need to know $B = \sum_{x} \lambda^{|I_x|}$.

Graphs with *n* vertices can have exponentially many independent sets calculating whose sum would be expensive task.

Markov chain here gives the stationary distribution by using only the ratios $\frac{\pi_y}{\pi_x}$.