Outline

## The class **NP**

## K. Subramani<sup>1</sup>

<sup>1</sup>Lane Department of Computer Science and Electrical Engineering West Virginia University

March 9 and March 16, 2015















2 The Class NP

3 Sample problems in NP



## Outline



2 The Class NP

3 Sample problems in NP

Search, Existence and Non-determinism



## Outline



2 The Class NP

3 Sample problems in NP

Search, Existence and Non-determinism



## Reductions

#### Reductions and Completeness The Class NP

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Reductions

### Main concept

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Reductions

### Main concept

Comparing problem difficulty through  $A \leq B$ .

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Reductions

### Main concept

Comparing problem difficulty through  $A \leq B$ .

When is problem B at least as hard as problem A?

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Reductions

### Main concept

Comparing problem difficulty through  $A \leq B$ .

When is problem B at least as hard as problem A?

When there is a transformation R, which for every input of A produces an equivalent input R(x) of B such that  $x \in A \Leftrightarrow R(x) \in B$ .

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Reductions

### Main concept

Comparing problem difficulty through  $A \leq B$ .

When is problem *B* at least as hard as problem *A*?

When there is a transformation R, which for every input of A produces an equivalent input R(x) of B such that  $x \in A \Leftrightarrow R(x) \in B$ .

#### Note

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Reductions

### Main concept

Comparing problem difficulty through  $A \leq B$ .

When is problem *B* at least as hard as problem *A*?

When there is a transformation R, which for every input of A produces an equivalent input R(x) of B such that  $x \in A \Leftrightarrow R(x) \in B$ .

#### Note

To be useful, R should have limitations. (Hamilton Path to Reachability).

#### Reductions and Completeness The Class NP

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## More on reductions

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## More on reductions

### Definition

Non-deterministic Polynomial Time Computational Complexity

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## More on reductions

### Definition

A language  $L_1$  is reducible to a language  $L_2$  if there is a function R from strings of  $L_1$  to strings of  $L_2$ , such that

$$(\forall x \in \Sigma_1^*) \ x \in L_1 \leftrightarrow R(x) \in L_2.$$

## More on reductions

### Definition

A language  $L_1$  is reducible to a language  $L_2$  if there is a function R from strings of  $L_1$  to strings of  $L_2$ , such that

$$(\forall x \in \Sigma_1^*) \ x \in L_1 \leftrightarrow R(x) \in L_2.$$

Furthermore, the function should be computable by an algorithm in  $O(\log n)$  space, on strings of length *n*.

## More on reductions

### Definition

A language  $L_1$  is reducible to a language  $L_2$  if there is a function R from strings of  $L_1$  to strings of  $L_2$ , such that

$$(\forall x \in \Sigma_1^*) \ x \in L_1 \leftrightarrow R(x) \in L_2.$$

Furthermore, the function should be computable by an algorithm in  $O(\log n)$  space, on strings of length *n*.

Note

## More on reductions

### Definition

A language  $L_1$  is reducible to a language  $L_2$  if there is a function R from strings of  $L_1$  to strings of  $L_2$ , such that

$$(\forall x \in \Sigma_1^*) \ x \in L_1 \leftrightarrow R(x) \in L_2.$$

Furthermore, the function should be computable by an algorithm in  $O(\log n)$  space, on strings of length *n*.

#### Note

Good old days, we used poly-time reductions.

## More on reductions

### Definition

A language  $L_1$  is reducible to a language  $L_2$  if there is a function R from strings of  $L_1$  to strings of  $L_2$ , such that

$$(\forall x \in \Sigma_1^*) \ x \in L_1 \leftrightarrow R(x) \in L_2.$$

Furthermore, the function should be computable by an algorithm in  $O(\log n)$  space, on strings of length *n*.

#### Note

Good old days, we used poly-time reductions.

#### Proposition

## More on reductions

#### Definition

A language  $L_1$  is reducible to a language  $L_2$  if there is a function R from strings of  $L_1$  to strings of  $L_2$ , such that

$$(\forall x \in \Sigma_1^*) \ x \in L_1 \leftrightarrow R(x) \in L_2.$$

Furthermore, the function should be computable by an algorithm in  $O(\log n)$  space, on strings of length *n*.

#### Note

Good old days, we used poly-time reductions.

#### Proposition

If R is a reduction computed by an algorithm A, then for all x, A halts after a polynomial number of steps.

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## **Composition of Reductions**

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

# **Composition of Reductions**

### Theorem

Non-deterministic Polynomial Time Computational Complexity

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## **Composition of Reductions**

### Theorem

If R is a reduction from  $L_1$  to  $L_2$  and R' is a reduction from  $L_2$  to  $L_3$ , then R'  $\circ$  R is a reduction from  $L_1$  to  $L_3$ .

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## **Composition of Reductions**

### Theorem

If R is a reduction from  $L_1$  to  $L_2$  and R' is a reduction from  $L_2$  to  $L_3$ , then R'  $\circ$  R is a reduction from  $L_1$  to  $L_3$ .

### Proof.

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## **Composition of Reductions**

### Theorem

If R is a reduction from  $L_1$  to  $L_2$  and R' is a reduction from  $L_2$  to  $L_3$ , then R'  $\circ$  R is a reduction from  $L_1$  to  $L_3$ .

### Proof.

Trivial for poly-time reductions.

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## **Composition of Reductions**

### Theorem

If R is a reduction from  $L_1$  to  $L_2$  and R' is a reduction from  $L_2$  to  $L_3$ , then R'  $\circ$  R is a reduction from  $L_1$  to  $L_3$ .

### Proof.

Trivial for poly-time reductions. Not so obvious for log-space reductions, since output of R(x) could be larger than  $\log |x|$ .

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## **Composition of Reductions**

### Theorem

If R is a reduction from  $L_1$  to  $L_2$  and R' is a reduction from  $L_2$  to  $L_3$ , then R'  $\circ$  R is a reduction from  $L_1$  to  $L_3$ .

### Proof.

Trivial for poly-time reductions. Not so obvious for log-space reductions, since output of R(x) could be larger than log |x|. Main idea:

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## **Composition of Reductions**

### Theorem

If R is a reduction from  $L_1$  to  $L_2$  and R' is a reduction from  $L_2$  to  $L_3$ , then R'  $\circ$  R is a reduction from  $L_1$  to  $L_3$ .

### Proof.

Trivial for poly-time reductions. Not so obvious for log-space reductions, since output of R(x) could be larger than log |x|. Main idea: Dovetail simulations.

#### Reductions and Completeness The Class NP

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Completeness

#### Reductions and Completeness The Class NP

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Completeness

### Definition

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Completeness

### Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Completeness

### Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

### Definition

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Completeness

### Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

### Definition

A complexity class  $\mathcal{C}$  is closed under reductions, if

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Completeness

### Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

### Definition

A complexity class  ${\mathcal C}$  is closed under reductions, if  $((L \in {\mathcal C}) \land (L' \leq L))$ 

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

## Completeness

#### Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

### Definition

A complexity class C is closed under reductions, if  $((L \in C) \land (L' \leq L)) \rightarrow (L' \in C)$ .

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

# Completeness

# Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

### Definition

A complexity class C is closed under reductions, if  $((L \in C) \land (L' \leq L)) \rightarrow (L' \in C)$ .

# Proposition

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

# Completeness

#### Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

#### Definition

A complexity class C is closed under reductions, if  $((L \in C) \land (L' \leq L)) \rightarrow (L' \in C)$ .

#### Proposition

P, NP, coNP, L, NL, PSPACE and EXP are all closed under reductions.

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

# Completeness

#### Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

#### Definition

A complexity class C is closed under reductions, if  $((L \in C) \land (L' \leq L)) \rightarrow (L' \in C)$ .

#### Proposition

P, NP, coNP, L, NL, PSPACE and EXP are all closed under reductions.

# Corollary

The Class NP Sample problems in NP Search, Existence and Non-determinism Linear Programming and Primality

# Completeness

#### Definition

A language L in a complexity class C is said to be C-complete, if any language  $L' \in C$  can be reduced to L.

#### Definition

A complexity class C is closed under reductions, if  $((L \in C) \land (L' \leq L)) \rightarrow (L' \in C)$ .

#### Proposition

P, NP, coNP, L, NL, PSPACE and EXP are all closed under reductions.

#### Corollary

If two classes C and C' are both closed under reductions and there exists a language L that is complete for both C and C' then C = C'.

# The class NP

# The class NP

# Definition

Non-deterministic Polynomial Time Computational Complexity

# The class NP

# Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

# The class NP

### Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

# Observations

Non-deterministic Polynomial Time Computational Complexity

# The class NP

### Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

#### Observations

O How to solve the Hamilton path problem efficiently?

# The class NP

# Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

#### Observations

How to solve the Hamilton path problem efficiently? Don't know.

# The class NP

#### Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

- How to solve the Hamilton path problem efficiently? Don't know.
- Suppose I give you a Hamilton path, can you verify its Hamiltonicity?

# The class NP

#### Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

- How to solve the Hamilton path problem efficiently? Don't know.
- Suppose I give you a Hamilton path, can you verify its Hamiltonicity?
- Output: Needle in a haystack analogy.

# The class NP

#### Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

- How to solve the Hamilton path problem efficiently? Don't know.
- Suppose I give you a Hamilton path, can you verify its Hamiltonicity?
- Needle in a haystack analogy.
- **O NP** is profoundly asymmetric.

# The class NP

#### Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

- How to solve the Hamilton path problem efficiently? Don't know.
- Suppose I give you a Hamilton path, can you verify its Hamiltonicity?
- Needle in a haystack analogy.
- **O NP** is profoundly asymmetric.
- $Is \mathbf{P} \subseteq \mathbf{NP}?$

# The class NP

#### Definition

A decision problem is in  $\ensuremath{\text{NP}}$ , if, whenever the answer for a particular instance is "yes", there is a simple proof of this fact.

- How to solve the Hamilton path problem efficiently? Don't know.
- Suppose I give you a Hamilton path, can you verify its Hamiltonicity?
- Needle in a haystack analogy.
- **O NP** is profoundly asymmetric.
- **(**) Is  $\mathbf{P} \subseteq \mathbf{NP}$ ? What is a short proof for a problem in  $\mathbf{P}$ ?

# Satisfiability

# Satisfiability

# SAT

Non-deterministic Polynomial Time Computational Complexity

# Satisfiability

# SAT

• A boolean variable is a variable that assumes the values **true** or **false**.

# Satisfiability

- A boolean variable is a variable that assumes the values **true** or **false**.
- **(2)** The complement of a boolean variable x is denoted by  $\bar{x}$  and assumes the value **true** if and only if the variable assumes **false**.

# Satisfiability

- A boolean variable is a variable that assumes the values true or false.
- **(3)** The complement of a boolean variable x is denoted by  $\bar{x}$  and assumes the value **true** if and only if the variable assumes **false**.
- A literal is a boolean variable or its complement.

# Satisfiability

- A boolean variable is a variable that assumes the values true or false.
- Or The complement of a boolean variable x is denoted by x and assumes the value true if and only if the variable assumes false.
- A literal is a boolean variable or its complement.
- A clause is a disjunction of literals.

# Satisfiability

- A boolean variable is a variable that assumes the values true or false.
- **(3)** The complement of a boolean variable x is denoted by  $\bar{x}$  and assumes the value **true** if and only if the variable assumes **false**.
- A literal is a boolean variable or its complement.
- A clause is a disjunction of literals.
- A boolean formula is said to be in Conjunctive Normal Form (CNF), if it is a conjunction of clauses.

# Satisfiability

- A boolean variable is a variable that assumes the values **true** or **false**.
- **(3)** The complement of a boolean variable x is denoted by  $\bar{x}$  and assumes the value **true** if and only if the variable assumes **false**.
- A literal is a boolean variable or its complement.
- A clause is a disjunction of literals.
- A boolean formula is said to be in Conjunctive Normal Form (CNF), if it is a conjunction of clauses.
- An assignment is a consistent mapping of the literals of a formula to true/false.

# Satisfiability

- A boolean variable is a variable that assumes the values **true** or **false**.
- O The complement of a boolean variable x is denoted by x and assumes the value true if and only if the variable assumes false.
- A literal is a boolean variable or its complement.
- A clause is a disjunction of literals.
- A boolean formula is said to be in Conjunctive Normal Form (CNF), if it is a conjunction of clauses.
- An assignment is a consistent mapping of the literals of a formula to true/false.
- A formula is said to be satisfiable, if it has a satisfying assignment.

# Satisfiability

# SAT A boolean variable is a variable that assumes the values true or false. The complement of a boolean variable x is denoted by x̄ and assumes the value true if and only if the variable assumes false. A literal is a boolean variable or its complement. A clause is a disjunction of literals. A boolean formula is said to be in Conjunctive Normal Form (CNF), if it is a conjunction of clauses.

- An assignment is a consistent mapping of the literals of a formula to true/false.
- A formula is said to be satisfiable, if it has a satisfying assignment.

# Definition

# Satisfiability

# SAT A boolean variable is a variable that assumes the values true or false. The complement of a boolean variable x is denoted by x and assumes the value true if and only if the variable assumes false. A literal is a boolean variable or its complement. A clause is a disjunction of literals. A boolean formula is said to be in Conjunctive Normal Form (CNF), if it is a conjunction of clauses. An assignment is a consistent mapping of the literals of a formula to true/false.

A formula is said to be satisfiable, if it has a satisfying assignment.

#### Definition

Given a CNF formula  $\phi = C_1 \land C_2 \ldots C_m$  over the *n* boolean variables  $\{x_1, x_2, \ldots, x_n\}$  and their complements, the satisfiability problem (or SAT) asks if  $\phi$  is satisfiable.

# Satisfiability

# SAT A boolean variable is a variable that assumes the values true or false. The complement of a boolean variable x is denoted by x and assumes the value true if and only if the variable assumes false. A literal is a boolean variable or its complement. A clause is a disjunction of literals. A boolean formula is said to be in Conjunctive Normal Form (CNF), if it is a conjunction of clauses. An assignment is a consistent mapping of the literals of a formula to true/false.

A formula is said to be satisfiable, if it has a satisfying assignment.

#### Definition

Given a CNF formula  $\phi = C_1 \land C_2 \ldots C_m$  over the *n* boolean variables  $\{x_1, x_2, \ldots, x_n\}$  and their complements, the satisfiability problem (or SAT) asks if  $\phi$  is satisfiable.

kSAT is the variant of SAT in which each clause has exactly k variables.

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# Variants of SAT

# Variants of SAT

# Exercise

Non-deterministic Polynomial Time Computational Complexity

# Variants of SAT

# Exercise

• Show that 1 SAT is in **P**.

# Variants of SAT

# Exercise

Show that 1 SAT is in **P**.

3 Show that the formula  $(p \lor \bar{q}) \land (\bar{p} \lor \bar{r}) \land (q \lor r) \land (p \lor q) \land (\bar{q} \lor r)$  is unsatisfiable.

# Variants of SAT

#### Exercise

- Show that 1 SAT is in **P**.
- 3 Show that the formula  $(p \lor \bar{q}) \land (\bar{p} \lor \bar{r}) \land (q \lor r) \land (p \lor q) \land (\bar{q} \lor r)$  is unsatisfiable.
- 3 A CNF formula is said to be Horn, if each clause has at most one positive literal.

# Variants of SAT

#### Exercise

- Show that 1 SAT is in **P**.
- 3 Show that the formula  $(p \lor \overline{q}) \land (\overline{p} \lor \overline{r}) \land (q \lor r) \land (p \lor q) \land (\overline{q} \lor r)$  is unsatisfiable.
- A CNF formula is said to be Horn, if each clause has at most one positive literal. Argue that HornSAT is in P.

# Variants of SAT

#### Exercise

- Show that 1 SAT is in **P**.
- 3 Show that the formula  $(p \lor \overline{q}) \land (\overline{p} \lor \overline{r}) \land (q \lor r) \land (p \lor q) \land (\overline{q} \lor r)$  is unsatisfiable.
- A CNF formula is said to be Horn, if each clause has at most one positive literal. Argue that HornSAT is in P.

#### Theorem

# Variants of SAT

#### Exercise

Show that 1 SAT is in **P**.

- 3 Show that the formula  $(p \lor \overline{q}) \land (\overline{p} \lor \overline{r}) \land (q \lor r) \land (p \lor q) \land (\overline{q} \lor r)$  is unsatisfiable.
- A CNF formula is said to be Horn, if each clause has at most one positive literal. Argue that HornSAT is in P.

#### Theorem

2SAT is in P.

# Variants of SAT

#### Exercise

Show that 1 SAT is in **P**.

- 3 Show that the formula  $(p \lor \overline{q}) \land (\overline{p} \lor \overline{r}) \land (q \lor r) \land (p \lor q) \land (\overline{q} \lor r)$  is unsatisfiable.
- A CNF formula is said to be Horn, if each clause has at most one positive literal. Argue that HornSAT is in P.

#### Theorem

2SAT is in P.

## Variants of SAT

### Exercise

Show that 1 SAT is in **P**.

- 3 Show that the formula  $(p \lor \overline{q}) \land (\overline{p} \lor \overline{r}) \land (q \lor r) \land (p \lor q) \land (\overline{q} \lor r)$  is unsatisfiable.
- A CNF formula is said to be Horn, if each clause has at most one positive literal. Argue that HornSAT is in P.

### Theorem

2SAT is in P.

### Observation

## Variants of SAT

### Exercise

## Show that 1 SAT is in **P**.

- 3 Show that the formula  $(p \lor \bar{q}) \land (\bar{p} \lor \bar{r}) \land (q \lor r) \land (p \lor q) \land (\bar{q} \lor r)$  is unsatisfiable.
- A CNF formula is said to be Horn, if each clause has at most one positive literal. Argue that HornSAT is in P.

### Theorem

2SAT is in P.

### Observation

$$(a \lor b) \quad \Leftrightarrow \quad (\bar{a} \to b)$$

## Variants of SAT

### Exercise

## Show that 1 SAT is in **P**.

- 3 Show that the formula  $(p \lor \bar{q}) \land (\bar{p} \lor \bar{r}) \land (q \lor r) \land (p \lor q) \land (\bar{q} \lor r)$  is unsatisfiable.
- A CNF formula is said to be Horn, if each clause has at most one positive literal. Argue that HornSAT is in P.

### Theorem

2SAT is in P.

### Observation

$$(a \lor b) \quad \Leftrightarrow \quad (\bar{a} \to b) \land (\bar{b} \to a)$$

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# **Implication Graph**

# **Implication Graph**

From constraints to Digraphs

# Implication Graph

From constraints to Digraphs

The implication graph  $G(\phi)$  corresponding to the formula  $\phi$  is created as follows:

# Implication Graph

### From constraints to Digraphs

The implication graph  $G(\phi)$  corresponding to the formula  $\phi$  is created as follows:

• Create one vertex for each literal; the vertex is labeled with the literal.

## Implication Graph

## From constraints to Digraphs

The implication graph  $G(\phi)$  corresponding to the formula  $\phi$  is created as follows:

- Oreate one vertex for each literal; the vertex is labeled with the literal.
- Orresponding to the clause (x<sub>i</sub> ∨ x<sub>j</sub>) draw a directed arc from x̄<sub>i</sub> to x<sub>j</sub> and another directed arc from x̄<sub>i</sub> to x<sub>i</sub>.

## Implication Graph

## From constraints to Digraphs

The implication graph  $G(\phi)$  corresponding to the formula  $\phi$  is created as follows:

- Create one vertex for each literal; the vertex is labeled with the literal.
- Orresponding to the clause (x<sub>i</sub> ∨ x<sub>j</sub>) draw a directed arc from x̄<sub>i</sub> to x<sub>j</sub> and another directed arc from x̄<sub>j</sub> to x<sub>i</sub>.
- The resultant graph is called the implication graph corresponding to the given 2CNF formula.

# Some observations

# Some observations

## Observations

Non-deterministic Polynomial Time Computational Complexity

# Some observations

## Observations

• If there is a path from literal *a* to literal *b* in  $G(\phi)$ , then there is also a path from  $\overline{b}$  to  $\overline{a}$ .

## Some observations

## Observations

- If there is a path from literal *a* to literal *b* in  $G(\phi)$ , then there is also a path from  $\overline{b}$  to  $\overline{a}$ .
- Any assignment which leads to a path from true to false is not a satisfying assignment.

## Some observations

## Observations

- If there is a path from literal *a* to literal *b* in  $G(\phi)$ , then there is also a path from  $\overline{b}$  to  $\overline{a}$ .
- Any assignment which leads to a path from true to false is not a satisfying assignment.
- If there is a path from x<sub>i</sub> to x̄<sub>i</sub>, then x<sub>i</sub> cannot be assigned true in a satisfying assignment.

## Some observations

## Observations

- If there is a path from literal *a* to literal *b* in  $G(\phi)$ , then there is also a path from  $\overline{b}$  to  $\overline{a}$ .
- Any assignment which leads to a path from true to false is not a satisfying assignment.
- If there is a path from x<sub>i</sub> to x̄<sub>i</sub>, then x<sub>i</sub> cannot be assigned true in a satisfying assignment.
- If there is a path from  $\bar{x_i}$  to  $x_i$ , then  $x_i$  cannot be assigned **false** in a satisfying assignment.

# **Reachability Lemmata**

# **Reachability Lemmata**

## Lemma

Non-deterministic Polynomial Time Computational Complexity

## **Reachability Lemmata**

### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa,

## **Reachability Lemmata**

### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

## **Reachability Lemmata**

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

## Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa,

## Reachability Lemmata

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

## Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is satisfiable.

## **Reachability Lemmata**

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

## Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is satisfiable.

### Proof.

## **Reachability Lemmata**

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

### Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is satisfiable.

### Proof.

• Assume that x is set to **true**, which means that there is no path from x to  $\bar{x}$ .

## Reachability Lemmata

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

### Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is satisfiable.

## Proof.

• Assume that x is set to **true**, which means that there is no path from x to  $\bar{x}$ .

**2** A contradiction occurs only if  $x \rightsquigarrow y$  and  $x \rightsquigarrow \overline{y}$  for some variable *y*.

## Reachability Lemmata

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

### Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is satisfiable.

## Proof.

- Assume that x is set to **true**, which means that there is no path from x to  $\bar{x}$ .
- **2** A contradiction occurs only if  $x \rightsquigarrow y$  and  $x \rightsquigarrow \overline{y}$  for some variable y.
- **3** By the symmetry of  $G(\phi)$ , there must be paths  $\bar{y} \rightsquigarrow \bar{x}$  and  $y \rightsquigarrow \bar{x}$ .

## **Reachability Lemmata**

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

### Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is satisfiable.

## Proof.

• Assume that x is set to **true**, which means that there is no path from x to  $\bar{x}$ .

- **2** A contradiction occurs only if  $x \rightsquigarrow y$  and  $x \rightsquigarrow \overline{y}$  for some variable y.
- **3** By the symmetry of  $G(\phi)$ , there must be paths  $\bar{y} \rightsquigarrow \bar{x}$  and  $y \rightsquigarrow \bar{x}$ .
- **(**) This means that there is a path  $x \rightsquigarrow \bar{x}$ ,

## **Reachability Lemmata**

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

### Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is satisfiable.

## Proof.

- Assume that x is set to **true**, which means that there is no path from x to  $\bar{x}$ .
- **2** A contradiction occurs only if  $x \rightsquigarrow y$  and  $x \rightsquigarrow \overline{y}$  for some variable y.
- **3** By the symmetry of  $G(\phi)$ , there must be paths  $\bar{y} \rightsquigarrow \bar{x}$  and  $y \rightsquigarrow \bar{x}$ .
- This means that there is a path  $x \rightsquigarrow \bar{x}$ , i.e., a contradiction.

## Reachability Lemmata

#### Lemma

If there is a variable x in  $G(\phi)$  such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is unsatisfiable.

### Lemma

If there is no variable x such that x is reachable from  $\bar{x}$  and vice versa, then  $\phi$  is satisfiable.

## Proof.

• Assume that x is set to **true**, which means that there is no path from x to  $\bar{x}$ .

- **2** A contradiction occurs only if  $x \rightsquigarrow y$  and  $x \rightsquigarrow \overline{y}$  for some variable y.
- **3** By the symmetry of  $G(\phi)$ , there must be paths  $\bar{y} \rightsquigarrow \bar{x}$  and  $y \rightsquigarrow \bar{x}$ .
- This means that there is a path  $x \rightsquigarrow \bar{x}$ , i.e., a contradiction.

The case where x is set to **false** can be handled similarly.

# The 2SAT Algorithm

FUNCTION 2SAT-ALGORITHM( $G(\phi)$ )

# The 2SAT Algorithm

FUNCTION 2SAT-ALGORITHM( $G(\phi)$ )

1: for (each variable x) do

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
1: for (each variable x) do
```

```
2: if (x \rightsquigarrow \overline{x})
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
```

- 1: for (each variable x) do
- 2: if  $(x \rightsquigarrow \overline{x})$  and  $(\overline{x} \rightsquigarrow x)$  then

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
```

- 1: for (each variable x) do
- 2: if  $(x \rightsquigarrow \overline{x})$  and  $(\overline{x} \rightsquigarrow x)$  then

```
3: return(false).
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
```

- 1: for (each variable x) do
- 2: if  $(x \rightsquigarrow \overline{x})$  and  $(\overline{x} \rightsquigarrow x)$  then
- 3: return(false).
- 4: end if

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
```

- 1: for (each variable x) do
- 2: if  $(x \rightsquigarrow \overline{x})$  and  $(\overline{x} \rightsquigarrow x)$  then
- 3: return(false).
- 4: end if
- 5: end for

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
```

- 1: for (each variable x) do
- 2: if  $(x \rightsquigarrow \overline{x})$  and  $(\overline{x} \rightsquigarrow x)$  then
- 3: return(false).
- 4: end if
- 5: end for
- 6: for (each variable x) do

```
FUNCTION 2SAT-ALGORITHM(G(\phi))

1: for (each variable x) do

2: if (x \rightsquigarrow \bar{x}) and (\bar{x} \rightsquigarrow x) then

3: return(false).

4: end if

5: end for

6: for (each variable x) do

7: if (x \rightsquigarrow \bar{x}) then
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))

1: for (each variable x) do

2: if (x \rightsquigarrow \bar{x}) and (\bar{x} \rightsquigarrow x) then

3: return(false).

4: end if

5: end for

6: for (each variable x) do

7: if (x \rightsquigarrow \bar{x}) then

8: x = false.
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
      if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
           return(false).
     end if
 4:
 5: end for
 6: for (each variable x) do
 7:
       if (x \rightsquigarrow \bar{x}) then
           x = false
 8.
       else
 g٠
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
      if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
           return(false).
        end if
 4:
 5: end for
 6: for (each variable x) do
 7:
        if (x \rightsquigarrow \bar{x}) then
           x = false
 8:
       else
 g٠
           if (\bar{x} \rightsquigarrow x) then
10:
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
      if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
           return(false).
        end if
 4:
 5: end for
 6: for (each variable x) do
 7:
        if (x \rightsquigarrow \bar{x}) then
           x = false
 8:
        else
 g٠
           if (\bar{x} \rightsquigarrow x) then
10:
              x = true.
11:
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
      if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
           return(false).
        end if
 4:
 5: end for
 6: for (each variable x) do
 7:
        if (x \rightsquigarrow \bar{x}) then
           x = false
 8:
        else
 g٠
           if (\bar{x} \rightsquigarrow x) then
10:
              x = true.
11:
         else
12:
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
        if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
           return(false).
        end if
 4:
 5: end for
 6: for (each variable x) do
 7:
        if (x \rightsquigarrow \bar{x}) then
           x = false
 8.
        else
 g٠
           if (\bar{x} \rightsquigarrow x) then
10:
              x = true.
11:
         else
12:
              Set x to true
13:
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
      if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
           return(false).
        end if
 4:
 5: end for
 6: for (each variable x) do
 7:
        if (x \rightsquigarrow \bar{x}) then
           x = false
 8.
        else
 g٠
           if (\bar{x} \rightsquigarrow x) then
10:
              x = true.
11.
         else
12:
              Set x to true or false.
13:
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
        if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
           return(false).
        end if
 4:
 5: end for
 6: for (each variable x) do
 7:
        if (x \rightsquigarrow \bar{x}) then
           x = false
 8.
        else
 g٠
           if (\bar{x} \rightsquigarrow x) then
10:
              x = true.
11:
12:
         else
              Set x to true or false.
13:
           end if
14.
```

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
       if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
           return(false).
       end if
 4:
 5: end for
 6: for (each variable x) do
 7:
       if (x \rightsquigarrow \bar{x}) then
           x = false
 8.
       else
 g٠
           if (\bar{x} \rightsquigarrow x) then
10:
              x = true.
11.
12:
        else
              Set x to true or false.
13:
           end if
14.
        end if
15:
```

## The 2SAT Algorithm

```
FUNCTION 2SAT-ALGORITHM(G(\phi))
 1: for (each variable x) do
       if (x \rightsquigarrow \overline{x}) and (\overline{x} \rightsquigarrow x) then
 2:
 3.
          return(false).
     end if
 4:
 5: end for
 6: for (each variable x) do
 7:
       if (x \rightsquigarrow \bar{x}) then
          x = false
 8.
      else
 g٠
          if (\bar{x} \rightsquigarrow x) then
10:
             x = true
11.
       else
12:
             Set x to true or false.
13:
          end if
14.
       end if
15:
16: end for
```

Algorithm 4.20: 2CNF satisfiability through Reachability

## Analysis

## Analysis

#### Exercise

What is the running time of the above algorithm?

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# Reducing Hamilton Path to SAT

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

## Reducing Hamilton Path to SAT

Hamilton Path to SAT

Input instance: An unweighted, directed graph G.

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

Suppose G has n nodes; φ has n<sup>2</sup> variables of the form x<sub>ij</sub>, where x<sub>ij</sub> represents the fact that node j is the i<sup>th</sup> node in the Hamilton Path (may or may not be true).

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

• Suppose *G* has *n* nodes;  $\phi$  has  $n^2$  variables of the form  $x_{ij}$ , where  $x_{ij}$  represents the fact that node *j* is the *i*<sup>th</sup> node in the Hamilton Path (may or may not be true).

**2** 
$$(x_{1j} \vee x_{2j} \dots x_{nj}), j = 1, 2, \dots, n.$$
 [*C*<sub>1</sub>]

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

• Suppose *G* has *n* nodes;  $\phi$  has  $n^2$  variables of the form  $x_{ij}$ , where  $x_{ij}$  represents the fact that node *j* is the *i*<sup>th</sup> node in the Hamilton Path (may or may not be true).

**2** 
$$(x_{1j} \vee x_{2j} \dots x_{nj}), j = 1, 2, \dots, n.$$
 [*C*<sub>1</sub>]

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

Suppose G has n nodes; φ has n<sup>2</sup> variables of the form x<sub>ij</sub>, where x<sub>ij</sub> represents the fact that node j is the i<sup>th</sup> node in the Hamilton Path (may or may not be true).

**2** 
$$(x_{1j} \lor x_{2j} \ldots x_{nj}), j = 1, 2, \ldots, n.$$
 [C<sub>1</sub>]

**③** 
$$(\neg x_{ij} \lor \neg x_{kj}), j = 1, 2..., n, i = 1, 2, ..., n, k = 1, 2, ..., n, k ≠ i. [C2].$$

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

Suppose G has n nodes; φ has n<sup>2</sup> variables of the form x<sub>ij</sub>, where x<sub>ij</sub> represents the fact that node j is the i<sup>th</sup> node in the Hamilton Path (may or may not be true).

**2** 
$$(x_{1j} \lor x_{2j} \ldots x_{nj}), j = 1, 2, \ldots, n.$$
 [*C*<sub>1</sub>]

**③** 
$$(\neg x_{ij} \lor \neg x_{kj}), j = 1, 2..., n, i = 1, 2, ..., n, k = 1, 2, ..., n, k ≠ i. [C2].$$

$$(x_{i1} \vee x_{i2} \ldots \vee x_{in}), i = 1, 2 \ldots n. \quad [C_3].$$

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

Suppose G has n nodes; φ has n<sup>2</sup> variables of the form x<sub>ij</sub>, where x<sub>ij</sub> represents the fact that node j is the i<sup>th</sup> node in the Hamilton Path (may or may not be true).

**2** 
$$(x_{1j} \vee x_{2j} \dots x_{nj}), j = 1, 2, \dots, n.$$
 [C<sub>1</sub>]

**③** 
$$(\neg x_{ij} \lor \neg x_{kj}), j = 1, 2..., n, i = 1, 2, ..., n, k = 1, 2, ..., n, k ≠ i. [C2].$$

$$(x_{i1} \vee x_{i2} \ldots \vee x_{in}), i = 1, 2 \ldots n. \quad [C_3].$$

**③**  $(\neg x_{ij} \lor \neg x_{ik}), i = 1, 2, ..., n, j, k = 1, 2, ..., n, j ≠ k. [C<sub>4</sub>].$ 

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

Suppose G has n nodes; φ has n<sup>2</sup> variables of the form x<sub>ij</sub>, where x<sub>ij</sub> represents the fact that node j is the i<sup>th</sup> node in the Hamilton Path (may or may not be true).

**2** 
$$(x_{1j} \lor x_{2j} \ldots x_{nj}), j = 1, 2, \ldots, n.$$
 [C<sub>1</sub>]

**③** 
$$(\neg x_{ij} \lor \neg x_{kj}), j = 1, 2..., n, i = 1, 2, ..., n, k = 1, 2, ..., n, k ≠ i. [C2].$$

$$(x_{i1} \vee x_{i2} \ldots \vee x_{in}), i = 1, 2 \ldots n. \quad [C_3]$$

**⑤** 
$$(\neg x_{ij} \lor \neg x_{ik}), i = 1, 2, ..., n, j, k = 1, 2, ..., n, j ≠ k. [C4].$$

**③** 
$$(\neg x_{ki} \lor \neg x_{(k+1)j}), k = 1, 2, ..., n-1, (i, j) ∉ G. [C_5].$$

## Reducing Hamilton Path to SAT

#### Hamilton Path to SAT

Input instance: An unweighted, directed graph *G*. Output instance: A CNF formula  $\phi$ , such that *G* has a Hamilton path if and only if  $\phi$  is satisfiable.

Suppose G has n nodes; φ has n<sup>2</sup> variables of the form x<sub>ij</sub>, where x<sub>ij</sub> represents the fact that node j is the i<sup>th</sup> node in the Hamilton Path (may or may not be true).

**2** 
$$(x_{1j} \lor x_{2j} \ldots x_{nj}), j = 1, 2, \ldots, n.$$
 [*C*<sub>1</sub>]

**③** 
$$(\neg x_{ij} \lor \neg x_{kj}), j = 1, 2..., n, i = 1, 2, ..., n, k = 1, 2, ..., n, k ≠ i. [C2].$$

$$(x_{i1} \vee x_{i2} \ldots \vee x_{in}), i = 1, 2 \ldots n. \quad [C_3]$$

**⑤** 
$$(\neg x_{ij} \lor \neg x_{ik}), i = 1, 2, ..., n, j, k = 1, 2, ..., n, j ≠ k. [C4].$$

**⑤** 
$$(\neg x_{ki} \lor \neg x_{(k+1)j}), k = 1, 2, ..., n-1, (i, j) ∉ G. [C_5].$$

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# Completing the argument

# Completing the argument

Satisfiability implies Hamilton Path

# Completing the argument

Satisfiability implies Hamilton Path

## Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

## Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

## Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

We show that there must exist a Hamilton Path in G.

• For each *j*, there is exactly one *i*, such that  $x_{ij}$  is **true** under *T*.

## Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

We show that there must exist a Hamilton Path in G.

• For each *j*, there is exactly one *i*, such that  $x_{ij}$  is **true** under *T*. (Why?)

#### Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

- For each *j*, there is exactly one *i*, such that  $x_{ij}$  is **true** under *T*. (Why?)
- 2 For each *i*, there is exactly one *j*, such that  $x_{ij}$  is **true** under *T*.

#### Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

- For each *j*, there is exactly one *i*, such that  $x_{ij}$  is **true** under *T*. (Why?)
- 2 For each *i*, there is exactly one *j*, such that  $x_{ij}$  is **true** under *T*. (Why?)

#### Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

- For each *j*, there is exactly one *i*, such that  $x_{ij}$  is **true** under *T*. (Why?)
- 2 For each *i*, there is exactly one *j*, such that  $x_{ij}$  is **true** under *T*. (Why?)
- **9** *T* is thus a permutation of the nodes  $(\pi(1), \pi(2), \ldots, \pi(n))$ , such that  $\pi(i) = j$  if and only if  $x_{ij}$  is set to **true** under *T*.

### Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

We show that there must exist a Hamilton Path in G.

- For each j, there is exactly one i, such that x<sub>ij</sub> is true under T. (Why?)
- 2 For each *i*, there is exactly one *j*, such that  $x_{ij}$  is **true** under *T*. (Why?)
- **9** *T* is thus a permutation of the nodes  $(\pi(1), \pi(2), \ldots, \pi(n))$ , such that  $\pi(i) = j$  if and only if  $x_{ij}$  is set to **true** under *T*.
- The clause system [*C*<sub>6</sub>] guarantees that adjacent elements on the permutation are connected by an edge in *G*.

### Completing the argument

Satisfiability implies Hamilton Path

Let T denote a satisfying assignment to  $\phi$ .

We show that there must exist a Hamilton Path in G.

- For each j, there is exactly one i, such that x<sub>ij</sub> is true under T. (Why?)
- 2 For each *i*, there is exactly one *j*, such that  $x_{ij}$  is **true** under *T*. (Why?)
- **9** *T* is thus a permutation of the nodes  $(\pi(1), \pi(2), \ldots, \pi(n))$ , such that  $\pi(i) = j$  if and only if  $x_{ij}$  is set to **true** under *T*.
- The clause system  $[C_6]$  guarantees that adjacent elements on the permutation are connected by an edge in *G*.
- It follows that *G* has a Hamilton path.

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# Completing the argument (contd.)

Completing the argument (contd.)

Hamilton Path implies Satisfiability

Assume that the graph *G* has a Hamilton path *p*.

Completing the argument (contd.)

#### Hamilton Path implies Satisfiability

Assume that the graph *G* has a Hamilton path *p*.

We show that  $\phi$  is satisfiable.

Completing the argument (contd.)

#### Hamilton Path implies Satisfiability

Assume that the graph *G* has a Hamilton path *p*.

We show that  $\phi$  is satisfiable. Observe that,

Completing the argument (contd.)

#### Hamilton Path implies Satisfiability

Assume that the graph *G* has a Hamilton path *p*.

We show that  $\phi$  is satisfiable. Observe that,

• Observe that *p* can be represented as a permutation  $\pi = (\pi(1), \pi(2) \dots \pi(n))$ , where  $\pi(i)$  represents the *i*<sup>th</sup> vertex on the Hamilton path.

## Completing the argument (contd.)

#### Hamilton Path implies Satisfiability

Assume that the graph *G* has a Hamilton path *p*.

We show that  $\phi$  is satisfiable. Observe that,

- Observe that *p* can be represented as a permutation  $\pi = (\pi(1), \pi(2) \dots \pi(n))$ , where  $\pi(i)$  represents the *i*<sup>th</sup> vertex on the Hamilton path.
- **2** Consider the following assignment:  $T(x_{ij}) =$  **true** if and only if  $\pi(i) = j$ .

Completing the argument (contd.)

#### Hamilton Path implies Satisfiability

Assume that the graph *G* has a Hamilton path *p*.

We show that  $\phi$  is satisfiable. Observe that,

- Observe that *p* can be represented as a permutation  $\pi = (\pi(1), \pi(2) \dots \pi(n))$ , where  $\pi(i)$  represents the *i*<sup>th</sup> vertex on the Hamilton path.
- **2** Consider the following assignment:  $T(x_{ij}) =$  **true** if and only if  $\pi(i) = j$ .

**③** It is not hard to see that every clause in  $\phi$  is satisfied.

## Completing the argument (contd.)

#### Hamilton Path implies Satisfiability

Assume that the graph *G* has a Hamilton path *p*.

We show that  $\phi$  is satisfiable. Observe that,

- Observe that *p* can be represented as a permutation  $\pi = (\pi(1), \pi(2) \dots \pi(n))$ , where  $\pi(i)$  represents the *i*<sup>th</sup> vertex on the Hamilton path.
- **2** Consider the following assignment:  $T(x_{ij}) =$  **true** if and only if  $\pi(i) = j$ .

**③** It is not hard to see that every clause in  $\phi$  is satisfied.

### Final Step

## Completing the argument (contd.)

#### Hamilton Path implies Satisfiability

Assume that the graph G has a Hamilton path p.

We show that  $\phi$  is satisfiable. Observe that,

- Observe that *p* can be represented as a permutation  $\pi = (\pi(1), \pi(2) \dots \pi(n))$ , where  $\pi(i)$  represents the *i*<sup>th</sup> vertex on the Hamilton path.
- **2** Consider the following assignment:  $T(x_{ij}) =$  **true** if and only if  $\pi(i) = j$ .

**③** It is not hard to see that every clause in  $\phi$  is satisfied.

#### Final Step

Is the reduction polynomial in the size of the input?

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# Boolean Circuits (Syntax)

# Boolean Circuits (Syntax)

### Syntax

Non-deterministic Polynomial Time Computational Complexity

# Boolean Circuits (Syntax)

### Syntax

• A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .

# Boolean Circuits (Syntax)

- A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .
- 2 The nodes  $V = \{1, 2, ..., n\}$  are called the gates of *C*.

# Boolean Circuits (Syntax)

- A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .
- 3 The nodes  $V = \{1, 2, ..., n\}$  are called the gates of *C*.
- We can assume without loss of generality that the edges are of the form (*i*, *j*), where *i* < *j*.

# Boolean Circuits (Syntax)

- A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .
- 3 The nodes  $V = \{1, 2, \dots n\}$  are called the gates of *C*.
- We can assume without loss of generality that the edges are of the form (*i*, *j*), where *i* < *j*.
- Each gate *i* has a sort s(i) associated with it, where  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, \ldots\} \cup \{\lor, \land, \neg\}.$

## **Boolean Circuits (Syntax)**

- A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .
- 2 The nodes  $V = \{1, 2, ..., n\}$  are called the gates of *C*.
- We can assume without loss of generality that the edges are of the form (*i*, *j*), where *i* < *j*.
- Each gate *i* has a sort s(i) associated with it, where  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, ...\} \cup \{\lor, \land, \neg\}.$
- If  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, ...\}$ , then its in-degree is 0.

## **Boolean Circuits (Syntax)**

- A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .
- 2 The nodes  $V = \{1, 2, ..., n\}$  are called the gates of *C*.
- We can assume without loss of generality that the edges are of the form (*i*, *j*), where *i* < *j*.
- Each gate *i* has a sort s(i) associated with it, where  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, \ldots\} \cup \{\lor, \land, \neg\}.$
- If  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, ...\}$ , then its in-degree is 0.
- If  $s(i) \in \{\neg\}$ , its in-degree is 1.

## **Boolean Circuits (Syntax)**

- A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .
- 2 The nodes  $V = \{1, 2, ..., n\}$  are called the gates of *C*.
- We can assume without loss of generality that the edges are of the form (*i*, *j*), where *i* < *j*.
- Each gate *i* has a sort s(i) associated with it, where  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, \ldots\} \cup \{\lor, \land, \neg\}.$
- If  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, ...\}$ , then its in-degree is 0.
- If  $s(i) \in \{\neg\}$ , its in-degree is 1.
- All other gates have in-degree 2.

## **Boolean Circuits (Syntax)**

- A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .
- 2 The nodes  $V = \{1, 2, ..., n\}$  are called the gates of *C*.
- We can assume without loss of generality that the edges are of the form (i, j), where i < j.</p>
- Each gate *i* has a sort s(i) associated with it, where  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, \ldots\} \cup \{\lor, \land, \neg\}.$
- If  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, ...\}$ , then its in-degree is 0.
- If  $s(i) \in \{\neg\}$ , its in-degree is 1.
- All other gates have in-degree 2.
- O All gates except gate n have out-degree 1.

## **Boolean Circuits (Syntax)**

- A boolean circuit *C* is a DAG  $G = \langle V, E \rangle$ .
- 2 The nodes  $V = \{1, 2, ..., n\}$  are called the gates of *C*.
- We can assume without loss of generality that the edges are of the form (i, j), where i < j.</p>
- Each gate *i* has a sort s(i) associated with it, where  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, \ldots\} \cup \{\lor, \land, \neg\}.$
- If  $s(i) \in \{$ true, false $\} \cup \{x_1, x_2, ...\}$ , then its in-degree is 0.
- If  $s(i) \in \{\neg\}$ , its in-degree is 1.
- All other gates have in-degree 2.
- O All gates except gate n have out-degree 1.
- Gate *n*, is called the output gate and has out-degree 0.

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# **Boolean Circuits (Semantics)**

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# **Boolean Circuits (Semantics)**

### Semantics

Non-deterministic Polynomial Time Computational Complexity

## **Boolean Circuits (Semantics)**

### Semantics

The semantics of circuits specifies a truth value for the circuit, corresponding to each appropriate assignment.

## **Boolean Circuits (Semantics)**

### Semantics

The semantics of circuits specifies a truth value for the circuit, corresponding to each appropriate assignment.

## **Boolean Circuits (Semantics)**

### Semantics

The semantics of circuits specifies a truth value for the circuit, corresponding to each appropriate assignment.

This value can be computed inductively as follows:

• If the gate is **true** or **false**, then it retains that value.

## **Boolean Circuits (Semantics)**

### Semantics

The semantics of circuits specifies a truth value for the circuit, corresponding to each appropriate assignment.

- If the gate is **true** or **false**, then it retains that value.
- 2 If the gate is a variable, then its value is equal to its assignment.

### **Boolean Circuits (Semantics)**

### Semantics

The semantics of circuits specifies a truth value for the circuit, corresponding to each appropriate assignment.

- If the gate is **true** or **false**, then it retains that value.
- 2 If the gate is a variable, then its value is equal to its assignment.
- **③** If the gate has sort  $\neg$ , then its value is the complement of its input.

### **Boolean Circuits (Semantics)**

### Semantics

The semantics of circuits specifies a truth value for the circuit, corresponding to each appropriate assignment.

- If the gate is **true** or **false**, then it retains that value.
- 2 If the gate is a variable, then its value is equal to its assignment.
- **③** If the gate has sort  $\neg$ , then its value is the complement of its input.
- If the gate has sort ∨, then its value is **true** if at least one of its two input gates has value **true** and is **false** otherwise.

### **Boolean Circuits (Semantics)**

#### Semantics

The semantics of circuits specifies a truth value for the circuit, corresponding to each appropriate assignment.

- If the gate is **true** or **false**, then it retains that value.
- 2 If the gate is a variable, then its value is equal to its assignment.
- If the gate has sort ¬, then its value is the complement of its input.
- If the gate has sort ∨, then its value is **true** if at least one of its two input gates has value **true** and is **false** otherwise.
- If the gate has sort ∧, then its value is true if both its two input gates have value true and is false otherwise.

### **Boolean Circuits (Semantics)**

#### Semantics

The semantics of circuits specifies a truth value for the circuit, corresponding to each appropriate assignment.

- If the gate is **true** or **false**, then it retains that value.
- If the gate is a variable, then its value is equal to its assignment.
- If the gate has sort ¬, then its value is the complement of its input.
- If the gate has sort ∨, then its value is true if at least one of its two input gates has value true and is false otherwise.
- If the gate has sort ∧, then its value is true if both its two input gates have value true and is false otherwise.
- The value of the circuit is the value of the output gate.

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# **CIRCUIT-SAT and CIRCUIT-VALUE**

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# **CIRCUIT-SAT and CIRCUIT-VALUE**

### Circuit-SAT

Non-deterministic Polynomial Time Computational Complexity

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# **CIRCUIT-SAT and CIRCUIT-VALUE**

#### Circuit-SAT

Given a circuit *C*, is there an assignment **true/false** to the variable gates, so that *C* evaluates to **true**?

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# **CIRCUIT-SAT and CIRCUIT-VALUE**

#### Circuit-SAT

Given a circuit *C*, is there an assignment **true/false** to the variable gates, so that *C* evaluates to **true**?

### Circuit-Value

Linear Programming and Primality

# **CIRCUIT-SAT and CIRCUIT-VALUE**

#### Circuit-SAT

Given a circuit *C*, is there an assignment **true/false** to the variable gates, so that *C* evaluates to **true**?

### Circuit-Value

Given a variable-free circuit C, does it evaluate to true?

Linear Programming and Primality

# **CIRCUIT-SAT and CIRCUIT-VALUE**

#### Circuit-SAT

Given a circuit *C*, is there an assignment **true/false** to the variable gates, so that *C* evaluates to **true**?

#### Circuit-Value

Given a variable-free circuit C, does it evaluate to true?

#### Exercise

Linear Programming and Primality

# **CIRCUIT-SAT and CIRCUIT-VALUE**

#### Circuit-SAT

Given a circuit *C*, is there an assignment **true/false** to the variable gates, so that *C* evaluates to **true**?

#### **Circuit-Value**

Given a variable-free circuit C, does it evaluate to true?

#### Exercise

Argue that CIRCUIT-VALUE is in P.

Linear Programming and Primality

# Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Non-deterministic Polynomial Time Computational Complexity

Linear Programming and Primality

## Reduction from CIRCUIT-SAT to SAT

CIRCUIT-SAT to SAT

Input instance: A circuit C.

### Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Input instance: A circuit C.

### Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Input instance: A circuit C.

Output instance: A CNF formula  $\phi$  such that  $\phi$  is satisfiable if and only if C is.

The variables of φ will contain all the variables of C. Additionally, for each gate g in C, we create a new variable in φ, also denoted by g.

### Reduction from CIRCUIT-SAT to SAT

#### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of φ will contain all the variables of C. Additionally, for each gate g in C, we create a new variable in φ, also denoted by g.
- **3** If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .

### Reduction from CIRCUIT-SAT to SAT

#### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of φ will contain all the variables of C. Additionally, for each gate g in C, we create a new variable in φ, also denoted by g.
- 3 If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .  $(g \Leftrightarrow x)$

## Reduction from CIRCUIT-SAT to SAT

#### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of  $\phi$  will contain all the variables of *C*. Additionally, for each gate *g* in *C*, we create a new variable in  $\phi$ , also denoted by *g*.
- **3** If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .  $(g \Leftrightarrow x)$
- 3 If g is a true gate, add (g) to  $\phi$ ; likewise, if it is a false gate, add ( $\neg g$ ).

## Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of  $\phi$  will contain all the variables of *C*. Additionally, for each gate *g* in *C*, we create a new variable in  $\phi$ , also denoted by *g*.
- **3** If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .  $(g \Leftrightarrow x)$
- 3 If g is a true gate, add (g) to  $\phi$ ; likewise, if it is a false gate, add ( $\neg g$ ).
- If g is a *NOT* gate with predecessor h, add the clauses  $(g \lor h)$  and  $(\neg g \lor \neg h)$  to  $\phi$ .

## Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of  $\phi$  will contain all the variables of *C*. Additionally, for each gate *g* in *C*, we create a new variable in  $\phi$ , also denoted by *g*.
- **3** If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .  $(g \Leftrightarrow x)$
- 3 If g is a true gate, add (g) to  $\phi$ ; likewise, if it is a false gate, add ( $\neg g$ ).
- If g is a *NOT* gate with predecessor h, add the clauses  $(g \lor h)$  and  $(\neg g \lor \neg h)$  to  $\phi$ .
- If g is an OR gate with predecessors h and h', add the clauses  $(\neg h \lor g)$ ,  $(\neg h' \lor g)$  and  $(h \lor h' \lor \neg g)$  to  $\phi$ .

## Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of  $\phi$  will contain all the variables of *C*. Additionally, for each gate *g* in *C*, we create a new variable in  $\phi$ , also denoted by *g*.
- **3** If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .  $(g \Leftrightarrow x)$
- 3 If g is a true gate, add (g) to  $\phi$ ; likewise, if it is a false gate, add ( $\neg g$ ).
- If g is a *NOT* gate with predecessor h, add the clauses  $(g \lor h)$  and  $(\neg g \lor \neg h)$  to  $\phi$ .
- If g is an OR gate with predecessors h and h', add the clauses  $(\neg h \lor g)$ ,  $(\neg h' \lor g)$  and  $(h \lor h' \lor \neg g)$  to  $\phi$ .  $(g \Leftrightarrow (h \lor h')$ .)

### Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of φ will contain all the variables of C. Additionally, for each gate g in C, we create a new variable in φ, also denoted by g.
- **3** If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .  $(g \Leftrightarrow x)$
- 3 If g is a true gate, add (g) to  $\phi$ ; likewise, if it is a false gate, add ( $\neg g$ ).
- If g is a *NOT* gate with predecessor h, add the clauses  $(g \lor h)$  and  $(\neg g \lor \neg h)$  to  $\phi$ .
- If g is an OR gate with predecessors h and h', add the clauses  $(\neg h \lor g)$ ,  $(\neg h' \lor g)$  and  $(h \lor h' \lor \neg g)$  to  $\phi$ .  $(g \Leftrightarrow (h \lor h')$ .)
- If g is an AND gate with predecessors h and h', add the clauses  $(\neg g \lor h)$ ,  $(\neg g \lor h')$  and  $(\neg h \lor \neg h' \lor g)$  to  $\phi$ .

### Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of φ will contain all the variables of C. Additionally, for each gate g in C, we create a new variable in φ, also denoted by g.
- **3** If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .  $(g \Leftrightarrow x)$
- 3 If g is a true gate, add (g) to  $\phi$ ; likewise, if it is a false gate, add ( $\neg g$ ).
- If g is a *NOT* gate with predecessor h, add the clauses  $(g \lor h)$  and  $(\neg g \lor \neg h)$  to  $\phi$ .
- If g is an OR gate with predecessors h and h', add the clauses  $(\neg h \lor g)$ ,  $(\neg h' \lor g)$  and  $(h \lor h' \lor \neg g)$  to  $\phi$ .  $(g \Leftrightarrow (h \lor h')$ .)
- If g is an AND gate with predecessors h and h', add the clauses  $(\neg g \lor h)$ ,  $(\neg g \lor h')$  and  $(\neg h \lor \neg h' \lor g)$  to  $\phi$ .  $(g \Leftrightarrow (h \land h').)$

## Reduction from CIRCUIT-SAT to SAT

### CIRCUIT-SAT to SAT

Input instance: A circuit C.

- The variables of  $\phi$  will contain all the variables of *C*. Additionally, for each gate *g* in *C*, we create a new variable in  $\phi$ , also denoted by *g*.
- **3** If *g* is a variable gate, corresponding to variable *x*, add the clauses  $(g \lor \neg x)$  and  $(\neg g \lor x)$  to  $\phi$ .  $(g \Leftrightarrow x)$
- 3 If g is a true gate, add (g) to  $\phi$ ; likewise, if it is a false gate, add ( $\neg g$ ).
- If g is a *NOT* gate with predecessor h, add the clauses  $(g \lor h)$  and  $(\neg g \lor \neg h)$  to  $\phi$ .
- **●** If *g* is an *OR* gate with predecessors *h* and *h'*, add the clauses  $(\neg h \lor g)$ ,  $(\neg h' \lor g)$  and  $(h \lor h' \lor \neg g)$  to  $\phi$ .  $(g \Leftrightarrow (h \lor h')$ .)
- If g is an AND gate with predecessors h and h', add the clauses  $(\neg g \lor h)$ ,  $(\neg g \lor h')$  and  $(\neg h \lor \neg h' \lor g)$  to  $\phi$ .  $(g \Leftrightarrow (h \land h').)$
- If g is an output gate, add the clause (g).

## Argument

## Argument

### Argument

Non-deterministic Polynomial Time Computational Complexity

## Argument

### Argument

**()** If *C* is satisfiable, then  $\phi$  is satisfiable.

## Argument

### Argument

- **()** If *C* is satisfiable, then  $\phi$  is satisfiable.
- **2** If  $\phi$  is satisfiable, then *C* is satisfiable.

# Graph coloring

Non-deterministic Polynomial Time Computational Complexity

# Graph coloring

The Graph coloring problem

## Graph coloring

### The Graph coloring problem

A coloring of an undirected graph  $G = \langle V, E \rangle$  is an assignment  $V \rightarrow \{1, 2, \dots, k\}$ .

## Graph coloring

#### The Graph coloring problem

A coloring of an undirected graph  $G = \langle V, E \rangle$  is an assignment  $V \rightarrow \{1, 2, \dots, k\}$ .

The coloring is said to be valid if no two adjacent vertices have the same color.

## Graph coloring

#### The Graph coloring problem

A coloring of an undirected graph  $G = \langle V, E \rangle$  is an assignment  $V \rightarrow \{1, 2, \dots, k\}$ .

The coloring is said to be valid if no two adjacent vertices have the same color.

In the GRAPH k-COLORING problem, you are given a number k and asked if G can be colored using k colors.

## Graph coloring

#### The Graph coloring problem

A coloring of an undirected graph  $G = \langle V, E \rangle$  is an assignment  $V \rightarrow \{1, 2, \dots, k\}$ .

The coloring is said to be valid if no two adjacent vertices have the same color.

In the GRAPH k-COLORING problem, you are given a number k and asked if G can be colored using k colors.

#### Exercise

### Graph coloring

#### The Graph coloring problem

A coloring of an undirected graph  $G = \langle V, E \rangle$  is an assignment  $V \rightarrow \{1, 2, \dots, k\}$ .

The coloring is said to be **valid** if no two adjacent vertices have the same color.

In the GRAPH k-COLORING problem, you are given a number k and asked if G can be colored using k colors.

#### Exercise

**O** Argue that GRAPH 2-COLORING is in **P**.

### Graph coloring

#### The Graph coloring problem

A coloring of an undirected graph  $G = \langle V, E \rangle$  is an assignment  $V \rightarrow \{1, 2, \dots, k\}$ .

The coloring is said to be **valid** if no two adjacent vertices have the same color.

In the GRAPH k-COLORING problem, you are given a number k and asked if G can be colored using k colors.

#### Exercise

- **O** Argue that GRAPH 2-COLORING is in **P**.
- **2** Argue that GRAPH 3-COLORING can be reduced to 3SAT.

Linear Programming and Primality

# 3-coloring to 3-SAT

# 3-coloring to 3-SAT

### Reduction

Non-deterministic Polynomial Time Computational Complexity

# 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

## 3-coloring to 3-SAT

### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

## 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

Let x<sub>ij</sub>, i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is true if vertex i gets color j, and false otherwise.

## 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

Let x<sub>ij</sub>, i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is true if vertex i gets color j, and false otherwise.

2 Every vertex should get at least one color.

# 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

Let x<sub>ij</sub>, i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is true if vertex i gets color j, and false otherwise.

2 Every vertex should get at least one color.

$$(x_{i1} \lor x_{i2} \lor x_{i3}), i = 1, 2, \ldots, n$$

# 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

Let x<sub>ij</sub>, i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is true if vertex i gets color j, and false otherwise.

2 Every vertex should get at least one color.

$$(x_{i1} \vee x_{i2} \vee x_{i3}), i = 1, 2, \ldots, n$$

Severy vertex should get at most one color.

## 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

Let x<sub>ij</sub>, i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is true if vertex i gets color j, and false otherwise.

2 Every vertex should get at least one color.

$$(x_{i1} \vee x_{i2} \vee x_{i3}), i = 1, 2, \ldots, n$$

Severy vertex should get at most one color.

## 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

Let x<sub>ij</sub>, i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is true if vertex i gets color j, and false otherwise.

2 Every vertex should get at least one color.

$$(x_{i1} \vee x_{i2} \vee x_{i3}), i = 1, 2, \ldots, n$$

Severy vertex should get at most one color.

$$\neg(x_{i1} \land x_{i2})$$

## 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

Let x<sub>ij</sub>, i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is true if vertex i gets color j, and false otherwise.

2 Every vertex should get at least one color.

$$(x_{i1} \lor x_{i2} \lor x_{i3}), i = 1, 2, \dots, n$$

Every vertex should get at most one color.

$$\neg (x_{i1} \land x_{i2}) \\ \neg (x_{i1} \land x_{i3})$$

## 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

Let x<sub>ij</sub>, i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is true if vertex i gets color j, and false otherwise.

2 Every vertex should get at least one color.

$$(x_{i1} \lor x_{i2} \lor x_{i3}), i = 1, 2, \dots, n$$

Every vertex should get at most one color.

$$\neg (x_{i1} \land x_{i2}) \neg (x_{i1} \land x_{i3}) \neg (x_{i2} \land x_{i3}),$$

## 3-coloring to 3-SAT

#### Reduction

**Input:** An undirected graph  $G = \langle V, E \rangle$ .

**Output:** A CNF formula  $\phi$ , such that  $\phi$  is satisfiable if and only if *G* has a valid 3-coloring.

• Let  $x_{ij}$ , i = 1, 2, ..., n, j = 1, 2, 3 be the boolean variable that is **true** if vertex *i* gets color *j*, and **false** otherwise.

2 Every vertex should get at least one color.

$$(x_{i1} \lor x_{i2} \lor x_{i3}), i = 1, 2, \dots, n$$

Every vertex should get at most one color.

$$\begin{array}{l} \neg (x_{i1} \land x_{i2}) \\ \neg (x_{i1} \land x_{i3}) \\ \neg (x_{i2} \land x_{i3}), i = 1, 2, \dots, n \end{array}$$

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# Completing the reduction

# Completing the reduction

Connectivity requirements

# Completing the reduction

#### Connectivity requirements

# Completing the reduction

#### Connectivity requirements

# Completing the reduction

### Connectivity requirements

$$\neg(x_{u1} \land x_{v1})$$

# Completing the reduction

### Connectivity requirements

$$\neg (x_{u1} \land x_{v1}) \\ \neg (x_{u2} \land x_{v2})$$

# Completing the reduction

### Connectivity requirements

$$\neg (x_{u1} \land x_{v1}) \neg (x_{u2} \land x_{v2}) \neg (x_{u3} \land x_{v3})$$

# Completing the reduction

### Connectivity requirements

If  $(u, v) \in E$ , then u and v should get different colors.

$$\begin{array}{rcl} \neg(x_{u1} & \wedge & x_{v1}) \\ \neg(x_{u2} & \wedge & x_{v2}) \\ \neg(x_{u3} & \wedge & x_{v3}) \\ (u,v) & \in & E \end{array}$$

A

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# Integer Partitioning and Subset Sum

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# Integer Partitioning and Subset Sum

### **Integer Partitioning**

Non-deterministic Polynomial Time Computational Complexity

## Integer Partitioning and Subset Sum

### **Integer Partitioning**

Given a list  $S = \{x_1, x_2, \dots, x_n\}$  of integers, is there a set  $A \subseteq S$ , such that  $\sum_{x_i \in A} x_i = \sum_{x_i \notin A} x_i$ ?

## Integer Partitioning and Subset Sum

### **Integer Partitioning**

Given a list  $S = \{x_1, x_2, ..., x_n\}$  of integers, is there a set  $A \subseteq S$ , such that  $\sum_{x_i \in A} x_i = \sum_{x_i \notin A} x_i$ ?

### Subset Sum

## Integer Partitioning and Subset Sum

#### **Integer Partitioning**

Given a list  $S = \{x_1, x_2, ..., x_n\}$  of integers, is there a set  $A \subseteq S$ , such that  $\sum_{x_i \in A} x_i = \sum_{x_i \notin A} x_i$ ?

### Subset Sum

Given a list  $S = \{x_1, x_2, ..., x_n\}$  of integers and a target *t*, is there a set  $A \subseteq S$ , such that  $\sum_{x_i \in A} x_i = t$ ?

## Integer Partitioning and Subset Sum

#### **Integer Partitioning**

Given a list  $S = \{x_1, x_2, ..., x_n\}$  of integers, is there a set  $A \subseteq S$ , such that  $\sum_{x_i \in A} x_i = \sum_{x_i \notin A} x_i$ ?

#### Subset Sum

Given a list  $S = \{x_1, x_2, ..., x_n\}$  of integers and a target *t*, is there a set  $A \subseteq S$ , such that  $\sum_{x_i \in A} x_i = t$ ?

#### Exercise

## Integer Partitioning and Subset Sum

#### **Integer Partitioning**

Given a list  $S = \{x_1, x_2, ..., x_n\}$  of integers, is there a set  $A \subseteq S$ , such that  $\sum_{x_i \in A} x_i = \sum_{x_i \notin A} x_i$ ?

#### Subset Sum

Given a list  $S = \{x_1, x_2, ..., x_n\}$  of integers and a target *t*, is there a set  $A \subseteq S$ , such that  $\sum_{x_i \in A} x_i = t$ ?

#### Exercise

Reduce INTEGER PARTITIONING to SUBSET SUM

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# **Binary Knapsack**

### Binary Knapsack

Non-deterministic Polynomial Time Computational Complexity

# **Binary Knapsack**

### **Binary Knapsack**

• You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .

## **Binary Knapsack**

- You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .
- 2 Object  $o_i$  has weight  $w_i$  and profit  $p_i$ .

## **Binary Knapsack**

- You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .
- **2** Object  $o_i$  has weight  $w_i$  and profit  $p_i$ .
- Solution You are also given a knapsack of weight capacity *W*.

### **Binary Knapsack**

- You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .
- **2** Object  $o_i$  has weight  $w_i$  and profit  $p_i$ .
- You are also given a knapsack of weight capacity *W*.
- The goal is to select a subset of the objects which does not violate the capacity constraint of the knapsack while maximizing the profit of the objects selected.

### **Binary Knapsack**

- You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .
- **2** Object  $o_i$  has weight  $w_i$  and profit  $p_i$ .
- You are also given a knapsack of weight capacity *W*.
- The goal is to select a subset of the objects which does not violate the capacity constraint of the knapsack while maximizing the profit of the objects selected.
- Profits are additive.

### **Binary Knapsack**

- You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .
- **2** Object  $o_i$  has weight  $w_i$  and profit  $p_i$ .
- You are also given a knapsack of weight capacity *W*.
- The goal is to select a subset of the objects which does not violate the capacity constraint of the knapsack while maximizing the profit of the objects selected.
- Profits are additive.
- O The integer programming formulation is:

## **Binary Knapsack**

- You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .
- **2** Object  $o_i$  has weight  $w_i$  and profit  $p_i$ .
- You are also given a knapsack of weight capacity *W*.
- The goal is to select a subset of the objects which does not violate the capacity constraint of the knapsack while maximizing the profit of the objects selected.
- Profits are additive.
- The integer programming formulation is:

max 
$$\sum_{i=1}^{n} p_i \cdot x_i$$

## **Binary Knapsack**

#### **Binary Knapsack**

- You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .
- **2** Object  $o_i$  has weight  $w_i$  and profit  $p_i$ .
- You are also given a knapsack of weight capacity *W*.
- The goal is to select a subset of the objects which does not violate the capacity constraint of the knapsack while maximizing the profit of the objects selected.
- Profits are additive.
- O The integer programming formulation is:

 $\begin{array}{ll} \max & \sum_{i=1}^{n} p_i \cdot x_i \\ \sum_{i=1}^{n} w_i \cdot x_i & \leq W \end{array}$ 

### **Binary Knapsack**

#### **Binary Knapsack**

- You are given *n* objects  $O = \{o_1, o_2, \ldots, o_n\}$ .
- **2** Object  $o_i$  has weight  $w_i$  and profit  $p_i$ .
- You are also given a knapsack of weight capacity *W*.
- The goal is to select a subset of the objects which does not violate the capacity constraint of the knapsack while maximizing the profit of the objects selected.
- Profits are additive.
- O The integer programming formulation is:

 $\max \qquad \sum_{i=1}^{n} p_i \cdot x_i \\ \sum_{i=1}^{n} w_i \cdot x_i \\ x_i = \{0, 1\} \quad \forall i = 1, 2, \dots, n$ 

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# Binary Knapsack (contd.)

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# Binary Knapsack (contd.)

### Exercise

Non-deterministic Polynomial Time Computational Complexity

## Binary Knapsack (contd.)

#### Exercise

Demonstrate through a counterexample that the greedy strategy used for fractional knapsack does not work in the binary knapsack case.

## Binary Knapsack (contd.)

#### Exercise

Demonstrate through a counterexample that the greedy strategy used for fractional knapsack does not work in the binary knapsack case.

### Solution

## Binary Knapsack (contd.)

#### Exercise

Demonstrate through a counterexample that the greedy strategy used for fractional knapsack does not work in the binary knapsack case.

### Solution

• Consider three objects  $o_1$ ,  $o_2$  and  $o_3$  with weights 10 units, 20 units and 30 units respectively and profits \$60, \$100 and \$120 respectively.

## Binary Knapsack (contd.)

#### Exercise

Demonstrate through a counterexample that the greedy strategy used for fractional knapsack does not work in the binary knapsack case.

- Consider three objects  $o_1$ ,  $o_2$  and  $o_3$  with weights 10 units, 20 units and 30 units respectively and profits \$60, \$100 and \$120 respectively.
- 2 Let the knapsack have weight capacity 50 units.

## Binary Knapsack (contd.)

#### Exercise

Demonstrate through a counterexample that the greedy strategy used for fractional knapsack does not work in the binary knapsack case.

- Consider three objects  $o_1$ ,  $o_2$  and  $o_3$  with weights 10 units, 20 units and 30 units respectively and profits \$60, \$100 and \$120 respectively.
- 2 Let the knapsack have weight capacity 50 units.
- The greedy solution is

## Binary Knapsack (contd.)

#### Exercise

Demonstrate through a counterexample that the greedy strategy used for fractional knapsack does not work in the binary knapsack case.

- Consider three objects  $o_1$ ,  $o_2$  and  $o_3$  with weights 10 units, 20 units and 30 units respectively and profits \$60, \$100 and \$120 respectively.
- 2 Let the knapsack have weight capacity 50 units.
- 3 The greedy solution is  $\{o_1, o_2\}$ .

## Binary Knapsack (contd.)

#### Exercise

Demonstrate through a counterexample that the greedy strategy used for fractional knapsack does not work in the binary knapsack case.

- Consider three objects  $o_1$ ,  $o_2$  and  $o_3$  with weights 10 units, 20 units and 30 units respectively and profits \$60, \$100 and \$120 respectively.
- 2 Let the knapsack have weight capacity 50 units.
- 3 The greedy solution is  $\{o_1, o_2\}$ .
- The optimal solution is

## Binary Knapsack (contd.)

#### Exercise

Demonstrate through a counterexample that the greedy strategy used for fractional knapsack does not work in the binary knapsack case.

- Consider three objects  $o_1$ ,  $o_2$  and  $o_3$  with weights 10 units, 20 units and 30 units respectively and profits \$60, \$100 and \$120 respectively.
- 2 Let the knapsack have weight capacity 50 units.
- 3 The greedy solution is  $\{o_1, o_2\}$ .
- The optimal solution is  $\{o_2, o_3\}$ .

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# A DP-based algorithm for binary knapsack

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

A DP-based algorithm for binary knapsack

A DP-based algorithm for binary knapsack

Principle of optimality

• Let KNAP(n, W) denote the given instance of the problem.

### A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- **2** Let  $S \subseteq O$  denote the optimal solution.

A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- **2** Let  $S \subseteq O$  denote the optimal solution.
- Focus on object o<sub>n</sub>.

### A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- **2** Let  $S \subseteq O$  denote the optimal solution.
- Focus on object on.
- Either  $o_n \in S$  or  $o_n \notin S$ .

### A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- 2 Let  $S \subseteq O$  denote the optimal solution.
- Focus on object o<sub>n</sub>.
- Either  $o_n \in S$  or  $o_n \notin S$ .
- **(**) If  $o_n \in S$ , then  $S \{o_n\}$  **must** constitute an optimal solution for

### A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- 2 Let  $S \subseteq O$  denote the optimal solution.
- Focus on object on.
- Either  $o_n \in S$  or  $o_n \notin S$ .
- If  $o_n \in S$ , then  $S \{o_n\}$  must constitute an optimal solution for KNAP $(n 1, W w_n)$ .

A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- 2 Let  $S \subseteq O$  denote the optimal solution.
- Focus on object on.
- Either  $o_n \in S$  or  $o_n \notin S$ .
- If  $o_n \in S$ , then  $S \{o_n\}$  must constitute an optimal solution for KNAP $(n 1, W w_n)$ . (Why?)

A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- 2 Let  $S \subseteq O$  denote the optimal solution.
- Focus on object on.
- Either  $o_n \in S$  or  $o_n \notin S$ .
- If o<sub>n</sub> ∈ S, then S {o<sub>n</sub>} must constitute an optimal solution for KNAP(n - 1, W - w<sub>n</sub>). (Why?)
- **(**) If  $o_n \notin S$ , then *S* **must** be an optimal solution for

A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- 2 Let  $S \subseteq O$  denote the optimal solution.
- Focus on object on.
- Either  $o_n \in S$  or  $o_n \notin S$ .
- If  $o_n \in S$ , then  $S \{o_n\}$  must constitute an optimal solution for KNAP $(n 1, W w_n)$ . (Why?)
- If  $o_n \notin S$ , then *S* must be an optimal solution for KNAP(n-1, n)

### A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- **2** Let  $S \subseteq O$  denote the optimal solution.
- Focus on object on.
- Either  $o_n \in S$  or  $o_n \notin S$ .
- If  $o_n \in S$ , then  $S \{o_n\}$  must constitute an optimal solution for KNAP $(n 1, W w_n)$ . (Why?)
- **●** If  $o_n \notin S$ , then *S* **must** be an optimal solution for KNAP(n 1, W).

A DP-based algorithm for binary knapsack

- Let KNAP(n, W) denote the given instance of the problem.
- 2 Let  $S \subseteq O$  denote the optimal solution.
- Focus on object on.
- Either  $o_n \in S$  or  $o_n \notin S$ .
- If  $o_n \in S$ , then  $S \{o_n\}$  must constitute an optimal solution for KNAP $(n 1, W w_n)$ . (Why?)
- If  $o_n \notin S$ , then S must be an optimal solution for KNAP(n-1, W). (Why?)

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Search, Existence and Non-determinism Linear Programming and Primality

# Formulating the recurrence

# Formulating the recurrence

#### The Recurrence

Non-deterministic Polynomial Time Computational Complexity

## Formulating the recurrence

#### The Recurrence

• Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.

## Formulating the recurrence

- Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.
- Which entry of the table are we interested in?

## Formulating the recurrence

- Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.
- **2** Which entry of the table are we interested in? Clearly, V[n, W].

### Formulating the recurrence

- Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.
- **2** Which entry of the table are we interested in? Clearly, V[n, W].
- As per the discussion above,

### Formulating the recurrence

- Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.
- **2** Which entry of the table are we interested in? Clearly, V[n, W].
- As per the discussion above,

$$V[i, w] = \max \left\{ \right.$$

### Formulating the recurrence

#### The Recurrence

• Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.

**2** Which entry of the table are we interested in? Clearly, V[n, W].

3 As per the discussion above,

$$V[i, w] = \max \left\{ V[i-1, w-w_i] + \rho_i \right\}$$

### Formulating the recurrence

- Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.
- **2** Which entry of the table are we interested in? Clearly, V[n, W].
- 3 As per the discussion above,

$$V[i, w] = \max \begin{cases} V[i-1, w-w_i] + p_i & (o_i \text{ is included}) \end{cases}$$

### Formulating the recurrence

- Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.
- **2** Which entry of the table are we interested in? Clearly, V[n, W].
- 3 As per the discussion above,

$$V[i, w] = \max \begin{cases} V[i-1, w-w_i] + p_i & (o_i \text{ is included}) \\ V[i-1, w] \end{cases}$$

### Formulating the recurrence

- Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.
- **2** Which entry of the table are we interested in? Clearly, V[n, W].
- 3 As per the discussion above,

$$V[i, w] = \max \begin{cases} V[i-1, w - w_i] + p_i & (o_i \text{ is included}) \\ V[i-1, w] & (o_i \text{ is excluded}) \end{cases}$$

### Formulating the recurrence

#### The Recurrence

- Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.
- 3 Which entry of the table are we interested in? Clearly, V[n, W].
- 3 As per the discussion above,

$$V[i, w] = \max \begin{cases} V[i-1, w-w_i] + p_i & (o_i \text{ is included}) \\ V[i-1, w] & (o_i \text{ is excluded}) \end{cases}$$

Initial conditions:

### Formulating the recurrence

#### The Recurrence

• Let V[i, w] denote the optimal solution for the subset  $\{o_1, o_2, \ldots, o_i\}$ , assuming that the Knapsack has a capacity w.

3 Which entry of the table are we interested in? Clearly, V[n, W].

3 As per the discussion above,

$$V[i, w] = \max \begin{cases} V[i-1, w-w_i] + p_i & (o_i \text{ is included}) \\ V[i-1, w] & (o_i \text{ is excluded}) \end{cases}$$

Initial conditions:

$$V[0,w] = 0, \quad 0 \le w \le W$$
  
bause $V[i,w] = -\infty, \quad w < 0$ 

# Example

## Example

#### Example

Non-deterministic Polynomial Time Computational Complexity

# Example

#### Example

Solve the following instance of Knapsack: n = 4,

# Example

#### Example

Solve the following instance of Knapsack: n = 4,  $\mathbf{w} = \langle 5, 4, 6, 3 \rangle$ ,

# Example

#### Example

Solve the following instance of Knapsack: n = 4,  $\mathbf{w} = \langle 5, 4, 6, 3 \rangle$ , W = 10,

# Example

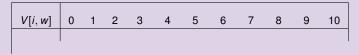
### Example

# Example

## Example

# Example

## Example



# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0											

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0	0	0	0	0	0	0	0	0	0	0	0

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0	0	0	0	0	0	0	0	0	0	0	0
1											

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0											
1	0	0	0	0	0						

# Example

## Example

		2	3	4	5	6	7	8	9	10
<i>i</i> = 0 0	0	0	0	0	0	0	0	0	0	0
1 0	0	0	0	0	10	10	10	10	10	10

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	10	10	10	10	10	10
2											

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	10	10	10	10	10	10
2	0	0	0	0							

# Example

## Example

V[i, w] $i = 0$ $1$ $2$	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	10	10	10	10	10	10
2	0	0	0	0	40	40	40	40	40	50	50

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
$\frac{V[i, w]}{i = 0}$ 1	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	10	10	10	10	10	10
2	0	0	0	0	40	40	40	40	40	50	50
3											

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0											
1	0	0	0	0	0	10	10	10	10	10	10
2											
3											

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	10	10	10	10	10	10
2	0	0	0	0	40	40	40	40	40	50	50
3	0	0	0	0	40	40	40	40	40	50	70

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0	0	0	0	0	0	0	0	0	0	0	0
1											
2	0	0	0	0	40	40	40	40	40	50	50
3					40						
4											

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
$\frac{V[i, w]}{i = 0}$	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	10	10	10	10	10	10
2	0	0	0	0	40	40	40	40	40	50	50
3	0	0	0	0	40	40	40	40	40	50	70
4	0	0	0								

# Example

## Example

V[i, w]	0	1	2	3	4	5	6	7	8	9	10
<i>i</i> = 0	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	10	10	10	10	10	10
2	0	0	0	0	40	40	40	40	40	50	50
3	0	0	0	0	40	40	40	40	40	50	70
4	0	0	0	50	50	50	50	90	90	90	90

# **Final observations**

Non-deterministic Polynomial Time Computational Complexity

# **Final observations**

#### Observation

Non-deterministic Polynomial Time Computational Complexity

# Final observations

#### Observation

• The running time of the DP-based algorithm for binary knapsack is

# **Final observations**

#### Observation

**①** The running time of the DP-based algorithm for binary knapsack is  $O(n \cdot W)$ .

# **Final observations**

- **①** The running time of the DP-based algorithm for binary knapsack is  $O(n \cdot W)$ .
- 2 Is the running time polynomial?

# **Final observations**

- **①** The running time of the DP-based algorithm for binary knapsack is  $O(n \cdot W)$ .
- Is the running time polynomial?
- **1** The Subset Sum problem can be easily reduced to binary knapsack.

# **Final observations**

- **①** The running time of the DP-based algorithm for binary knapsack is  $O(n \cdot W)$ .
- Is the running time polynomial?
- The Subset Sum problem can be easily reduced to binary knapsack. How?

# **Final observations**

- **①** The running time of the DP-based algorithm for binary knapsack is  $O(n \cdot W)$ .
- Is the running time polynomial?
- The Subset Sum problem can be easily reduced to binary knapsack. How?
- **(**) We thus have, INTEGER PARTITION  $\leq$  SUBSET SUM  $\leq$  BINARY KNAPSACK.

Reductions and Completeness The Class NP Sample problems in NP

Search, Existence and Non-determinism Linear Programming and Primality

# Three related graph problems

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# Three related graph problems

Vertex Cover (VC)

# Three related graph problems

#### Vertex Cover (VC)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \leq K$ , such that for every edge  $(u, v) \in E$ , either  $u \in V'$  or  $v \in V'$ ?

# Three related graph problems

#### Vertex Cover (VC)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \leq K$ , such that for every edge  $(u, v) \in E$ , either  $u \in V'$  or  $v \in V'$ ?

## Independent Set (IS)

# Three related graph problems

#### Vertex Cover (VC)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \leq K$ , such that for every edge  $(u, v) \in E$ , either  $u \in V'$  or  $v \in V'$ ?

#### Independent Set (IS)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \ge K$ , such that for every pair of vertices  $(u, v) \in V'$ ,  $(u, v) \notin E$ .

## Three related graph problems

#### Vertex Cover (VC)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \leq K$ , such that for every edge  $(u, v) \in E$ , either  $u \in V'$  or  $v \in V'$ ?

#### Independent Set (IS)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \ge K$ , such that for every pair of vertices  $(u, v) \in V'$ ,  $(u, v) \notin E$ .

### Clique (CQ)

# Three related graph problems

#### Vertex Cover (VC)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \leq K$ , such that for every edge  $(u, v) \in E$ , either  $u \in V'$  or  $v \in V'$ ?

#### Independent Set (IS)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \ge K$ , such that for every pair of vertices  $(u, v) \in V'$ ,  $(u, v) \notin E$ .

#### Clique (CQ)

Given a graph  $G = \langle V, E \rangle$  and a number K, is there a set  $V' \subseteq V$ ,  $|V'| \leq K$ , such that for pair of vertices  $(u, v) \in V'$ ,  $(u, v) \in E$ .

Reductions and Completeness The Class NP Sample problems in NP Search, Existence and Non-determinism

Linear Programming and Primality

# Observation relating the three problems

# Observation relating the three problems

#### Theorem

Non-deterministic Polynomial Time Computational Complexity

Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

# Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

The following statements are equivalent:

# Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

The following statements are equivalent:

S is a vertex cover.

# Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

The following statements are equivalent:

- S is a vertex cover.
- **2** V S is an independent set.

# Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

The following statements are equivalent:

- S is a vertex cover.
- **2** V S is an independent set.
- V S is a clique in G<sup>c</sup> = (V, E<sup>c</sup>), where two vertices are adjacent in G<sup>c</sup> if and only if they are non-adjacent in G.

# Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

The following statements are equivalent:

- S is a vertex cover.
- V S is an independent set.
- V S is a clique in G<sup>c</sup> = (V, E<sup>c</sup>), where two vertices are adjacent in G<sup>c</sup> if and only if they are non-adjacent in G.

#### Exercise

# Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

The following statements are equivalent:

- S is a vertex cover.
- V S is an independent set.
- V S is a clique in G<sup>c</sup> = (V, E<sup>c</sup>), where two vertices are adjacent in G<sup>c</sup> if and only if they are non-adjacent in G.

#### Exercise

• Argue that  $VC \leq IS \leq CQ$ .

# Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

The following statements are equivalent:

- S is a vertex cover.
- V S is an independent set.
- V S is a clique in G<sup>c</sup> = (V, E<sup>c</sup>), where two vertices are adjacent in G<sup>c</sup> if and only if they are non-adjacent in G.

#### Exercise

- Argue that  $VC \leq IS \leq CQ$ .
- Show that if a graph is k-colorable, then it has an independent set of size at least  $\frac{n}{k}$ .

# Observation relating the three problems

#### Theorem

Let  $G = \langle V, E \rangle$  denote a graph and let  $S \subseteq V$ .

The following statements are equivalent:

- S is a vertex cover.
- V S is an independent set.
- V S is a clique in G<sup>c</sup> = (V, E<sup>c</sup>), where two vertices are adjacent in G<sup>c</sup> if and only if they are non-adjacent in G.

#### Exercise

- Argue that  $VC \leq IS \leq CQ$ .
- 3 Show that if a graph is k-colorable, then it has an independent set of size at least  $\frac{n}{k}$ . Is the converse true.

# First Formal Definition

# First Formal Definition

#### Definition

Non-deterministic Polynomial Time Computational Complexity

# **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

# **First Formal Definition**

#### Definition

**NP** is the class of problems A of the following form:

x is a yes-instance of A if and only if there exists a w,

# **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

## **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

Observations

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

• w is a witness of the fact that x is a yes-instance.

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

• w is a witness of the fact that x is a yes-instance. It is called a certificate.

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

• *w* is a witness of the fact that *x* is a yes-instance. It is called a certificate.

B is the problem of checking whether x is a genuine needle.

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

- *w* is a witness of the fact that *x* is a yes-instance. It is called a certificate.
- **3** *B* is the problem of checking whether x is a genuine needle. For instance, if A is HAMILTON-PATH, then x is a graph,

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

- *w* is a witness of the fact that *x* is a yes-instance. It is called a certificate.
- **3** *B* is the problem of checking whether x is a genuine needle. For instance, if A is HAMILTON-PATH, then x is a graph, w is a path,

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

• w is a witness of the fact that x is a yes-instance. It is called a certificate.

B is the problem of checking whether x is a genuine needle. For instance, if A is HAMILTON-PATH, then x is a graph, w is a path, and B is the problem of checking whether w is a valid Hamilton path for x.

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

• w is a witness of the fact that x is a yes-instance. It is called a certificate.

B is the problem of checking whether x is a genuine needle. For instance, if A is HAMILTON-PATH, then x is a graph, w is a path, and B is the problem of checking whether w is a valid Hamilton path for x.

W is required to be polynomially balanced.

### **First Formal Definition**

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

• w is a witness of the fact that x is a yes-instance. It is called a certificate.

B is the problem of checking whether x is a genuine needle. For instance, if A is HAMILTON-PATH, then x is a graph, w is a path, and B is the problem of checking whether w is a valid Hamilton path for x.

• w is required to be polynomially balanced. This ensures that B runs in time polynomial in |x|.

## First Formal Definition

#### Definition

**NP** is the class of problems *A* of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **P** regarding pairs (x, w) and |w| = poly(|x|).

#### Observations

• w is a witness of the fact that x is a yes-instance. It is called a certificate.

B is the problem of checking whether x is a genuine needle. For instance, if A is HAMILTON-PATH, then x is a graph, w is a path, and B is the problem of checking whether w is a valid Hamilton path for x.

• w is required to be polynomially balanced. This ensures that B runs in time polynomial in |x|.

**O** NP  $\subseteq$  EXP, where EXP=TIME(2<sup>poly(n)</sup>).



# Generalizing NP

#### Definition

Non-deterministic Polynomial Time Computational Complexity

# Generalizing NP

#### Definition

**NTIME**(f(n)) is the class of problems A of the following form:

# Generalizing NP

#### Definition

**NTIME**(f(n)) is the class of problems A of the following form:

x is a yes-instance of A if and only if there exists a w,

# Generalizing NP

#### Definition

**NTIME**(f(n)) is the class of problems A of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

# Generalizing NP

#### Definition

**NTIME**(f(n)) is the class of problems A of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **TIME**(f(n) regarding pairs (x, w), |x| = n and |w| = O(f(n)).

# Generalizing NP

#### Definition

**NTIME**(f(n)) is the class of problems A of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **TIME**(f(n) regarding pairs (x, w), |x| = n and |w| = O(f(n)).

As argued previously,

# Generalizing NP

#### Definition

**NTIME**(f(n)) is the class of problems A of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **TIME**(f(n) regarding pairs (x, w), |x| = n and |w| = O(f(n)).

As argued previously,

 $\mathsf{NTIME}(f(n)) \subseteq \mathsf{TIME}(2^{f(n)})$ 

# Generalizing NP

#### Definition

**NTIME**(f(n)) is the class of problems A of the following form:

x is a yes-instance of A if and only if there exists a w, such that (x, w) is is a yes-instance of B,

where *B* is a decision problem in **TIME**(f(n) regarding pairs (x, w), |x| = n and |w| = O(f(n)).

As argued previously,

 $\mathsf{NTIME}(f(n)) \subseteq \mathsf{TIME}(2^{f(n)})$ 

# Another definition for NP

# Another definition for NP

#### Definition

Non-deterministic Polynomial Time Computational Complexity

# Another definition for NP

#### Definition

NP is the class of properties A of the form

# Another definition for NP

#### Definition

NP is the class of properties A of the form

 $A(x) = \exists w : B(x, w)$ 

## Another definition for NP

#### Definition

NP is the class of properties A of the form

$$A(x) = \exists w : B(x, w)$$

where *B* is in **P** and where |w| = poly(|x|).

## Some observations

## Some observations

#### Observations

Non-deterministic Polynomial Time Computational Complexity

## Some observations

#### Observations

• We have associated with the decision problem A, the property A(x), where A(x) is **true** if and only if x is a yes-instance of A.

## Some observations

#### Observations

• We have associated with the decision problem A, the property A(x), where A(x) is **true** if and only if x is a yes-instance of A.

## Some observations

#### Observations

• We have associated with the decision problem A, the property A(x), where A(x) is **true** if and only if x is a yes-instance of A.

For instance, if x is a graph and A(x) is the property that x has a Hamilton path, then B(x, w) is the polynomial time property that w is a Hamilton path for x.

3 Algorithmically, the quantifier  $\exists$  represents the process of searching for the witness *w*.

## Some observations

#### Observations

We have associated with the decision problem A, the property A(x), where A(x) is true if and only if x is a yes-instance of A.

- 3 Algorithmically, the quantifier  $\exists$  represents the process of searching for the witness *w*.
- Prover-Verifier conversation.

## Some observations

#### Observations

We have associated with the decision problem A, the property A(x), where A(x) is true if and only if x is a yes-instance of A.

- **3** Algorithmically, the quantifier  $\exists$  represents the process of searching for the witness *w*.
- Prover-Verifier conversation.
- Are the complements of P properties in P?

## Some observations

#### Observations

• We have associated with the decision problem A, the property A(x), where A(x) is **true** if and only if x is a yes-instance of A.

- 3 Algorithmically, the quantifier  $\exists$  represents the process of searching for the witness *w*.
- Prover-Verifier conversation.
- Are the complements of P properties in P?
- O How about complements of NP properties? These properties belong to the class coNP; they have easy to check no instances, but no known method of verifying yes-instances in polynomial time.

## Exercise

#### Exercise

Non-deterministic Polynomial Time Computational Complexity

## Exercise

#### Exercise

• Is coNP the complement of NP?

## Exercise

- Is coNP the complement of NP?
- **2** Is  $NP \cap coNP$  identical to P?

## Exercise

- Is coNP the complement of NP?
- **2** Is  $NP \cap coNP$  identical to P?
- **3** Show that if  $\mathbf{P} = \mathbf{NP}$  then  $\mathbf{NP} = \mathbf{coNP}$ .

## Exercise

- Is coNP the complement of NP?
- **2** Is  $NP \cap coNP$  identical to P?
- Show that if P = NP then NP = coNP. Is the converse true?

## Nondeterministic Computation

## Nondeterministic Computation

#### **Fundamentals**

Non-deterministic Polynomial Time

## Nondeterministic Computation

#### **Fundamentals**

• A computer program is deterministic in that given the initial state and input, the execution trace is fixed, i.e., there are no choices for the program to make.

## Nondeterministic Computation

#### **Fundamentals**

- A computer program is deterministic in that given the initial state and input, the execution trace is fixed, i.e., there are no choices for the program to make.
- 2 A nondeterministic program can make several possible choices at each step.

## Nondeterministic Computation

#### **Fundamentals**

- A computer program is deterministic in that given the initial state and input, the execution trace is fixed, i.e., there are no choices for the program to make.
- A nondeterministic program can make several possible choices at each step. For instance, consider the instruction:

## Nondeterministic Computation

#### **Fundamentals**

- A computer program is deterministic in that given the initial state and input, the execution trace is fixed, i.e., there are no choices for the program to make.
- A nondeterministic program can make several possible choices at each step. For instance, consider the instruction:

goto both line<sub>1</sub>, line<sub>2</sub>.

## Nondeterministic Computation

#### **Fundamentals**

- A computer program is deterministic in that given the initial state and input, the execution trace is fixed, i.e., there are no choices for the program to make.
- A nondeterministic program can make several possible choices at each step. For instance, consider the instruction:

goto both line<sub>1</sub>, line<sub>2</sub>.

The computation then becomes a tree instead of a straight line.

## Nondeterministic Computation

#### **Fundamentals**

- A computer program is deterministic in that given the initial state and input, the execution trace is fixed, i.e., there are no choices for the program to make.
- A nondeterministic program can make several possible choices at each step. For instance, consider the instruction:

goto both line<sub>1</sub>, line<sub>2</sub>.

- The computation then becomes a tree instead of a straight line.
- The output of a nondeterministic program is "yes", if any of the computations in the tree leads to a an accepting state and "no" otherwise.

## Nondeterministic Computation

#### **Fundamentals**

- A computer program is deterministic in that given the initial state and input, the execution trace is fixed, i.e., there are no choices for the program to make.
- A nondeterministic program can make several possible choices at each step. For instance, consider the instruction:

goto both line<sub>1</sub>, line<sub>2</sub>.

- The computation then becomes a tree instead of a straight line.
- The output of a nondeterministic program is "yes", if any of the computations in the tree leads to a an accepting state and "no" otherwise.
- The running time of a nondeterministic program is the height of its computation tree.

## Nondeterministic Computation

#### **Fundamentals**

- A computer program is deterministic in that given the initial state and input, the execution trace is fixed, i.e., there are no choices for the program to make.
- A nondeterministic program can make several possible choices at each step. For instance, consider the instruction:

#### goto both line<sub>1</sub>, line<sub>2</sub>.

- The computation then becomes a tree instead of a straight line.
- The output of a nondeterministic program is "yes", if any of the computations in the tree leads to a an accepting state and "no" otherwise.
- The running time of a nondeterministic program is the height of its computation tree.

#### Exercise

Write a nondeterministic program for 3SAT.

## Final definition of NP

## Final definition of NP

#### Definition

## Final definition of NP

#### Definition

**NP** is the class of problems for which a nondeterministic program exists that runs in time poly(n), on instances of length *n*,

## Final definition of NP

#### Definition

**NP** is the class of problems for which a nondeterministic program exists that runs in time poly(n), on instances of length *n*, such that the input is a yes-instance if and only if there exists a computation path that returns "yes."

## Final definition of NP

#### Definition

**NP** is the class of problems for which a nondeterministic program exists that runs in time poly(n), on instances of length *n*, such that the input is a yes-instance if and only if there exists a computation path that returns "yes."

#### Definition

## Final definition of NP

#### Definition

**NP** is the class of problems for which a nondeterministic program exists that runs in time poly(n), on instances of length *n*, such that the input is a yes-instance if and only if there exists a computation path that returns "yes."

#### Definition

**NTIME**(f(n)) is the class of problems for which a nondeterministic program exists that runs in time O(f(n)), on instances of length *n*,

## Final definition of NP

#### Definition

**NP** is the class of problems for which a nondeterministic program exists that runs in time poly(n), on instances of length *n*, such that the input is a yes-instance if and only if there exists a computation path that returns "yes."

#### Definition

**NTIME**(f(n)) is the class of problems for which a nondeterministic program exists that runs in time O(f(n)), on instances of length *n*, such that the input is a yes-instance if and only if there exists a computation path that returns "yes."

## Linear Programming

## Linear Programming

#### The Problem (LP)

Non-deterministic Polynomial Time Computational Complexity

## Linear Programming

## The Problem (LP) $\exists x \ A \cdot x \leq b$ $x \geq 0$

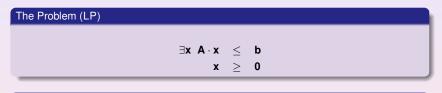
## Linear Programming

# The Problem (LP) $\exists \mathbf{x} \ \mathbf{A} \cdot \mathbf{x} \leq \mathbf{b} \\ \mathbf{x} > \mathbf{0}$

#### Observation

Non-deterministic Polynomial Time Computational Complexity

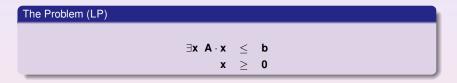
# Linear Programming



### Observation

● Is LP in NP?

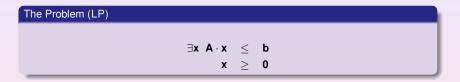
## Linear Programming



#### Observation

● Is LP in NP? Does Guess and Verify work?

# Linear Programming



### Observation

- Is LP in NP? Does Guess and Verify work?
- **2** Is LP in **coNP**?

# Complexity

# Complexity

### Fundamentals

Non-deterministic Polynomial Time Computational Complexity

# Complexity

### Fundamentals

• Assume that **A** has *m* rows and *n* columns.

## Complexity

### Fundamentals

- Assume that **A** has *m* rows and *n* columns.
- Observe that with the introduction of slack variables, we can rewrite the Linear programming problem as:

$$\begin{array}{rcl} \exists \mathbf{x} \ \mathbf{A} \cdot \mathbf{x} &= \mathbf{b} \\ \mathbf{x} &> \mathbf{0} \end{array}$$

## Complexity

#### **Fundamentals**

- Assume that **A** has *m* rows and *n* columns.
- Observe that with the introduction of slack variables, we can rewrite the Linear programming problem as:

$$\begin{array}{rcl} \mathbf{A} \cdot \mathbf{X} &= & \mathbf{b} \\ \mathbf{x} &\geq & \mathbf{0} \end{array}$$

where  $m \leq n$ 

3 A basis of the above system is a collection of *m* linearly independent columns.

## Complexity

#### **Fundamentals**

- Assume that **A** has *m* rows and *n* columns.
- Observe that with the introduction of slack variables, we can rewrite the Linear programming problem as:

$$\begin{array}{rcl} \mathbf{A} \cdot \mathbf{X} &= & \mathbf{b} \\ \mathbf{x} &\geq & \mathbf{0} \end{array}$$

- 3 A basis of the above system is a collection of *m* linearly independent columns.
- **(**) A basic solution is obtained by solving the system  $\mathbf{B} \cdot \mathbf{x}_{\mathbf{B}} + \mathbf{N} \cdot \mathbf{x}_{\mathbf{N}} = \mathbf{b}, \mathbf{x}_{\mathbf{N}} = \mathbf{0}$ .

## Complexity

#### **Fundamentals**

- Assume that **A** has *m* rows and *n* columns.
- Observe that with the introduction of slack variables, we can rewrite the Linear programming problem as:

$$\begin{array}{rcl} \exists \mathbf{x} \ \ \mathbf{A} \cdot \mathbf{x} &= \mathbf{b} \\ \mathbf{x} &\geq \mathbf{0} \end{array}$$

- A basis of the above system is a collection of *m* linearly independent columns.
- **(**) A basic solution is obtained by solving the system  $\mathbf{B} \cdot \mathbf{x}_{\mathbf{B}} + \mathbf{N} \cdot \mathbf{x}_{\mathbf{N}} = \mathbf{b}, \mathbf{x}_{\mathbf{N}} = \mathbf{0}$ .
- **O** The basic solution is feasible if every element of **x**<sub>B</sub> is non-negative.

## Complexity

#### **Fundamentals**

- Assume that A has m rows and n columns.
- Observe that with the introduction of slack variables, we can rewrite the Linear programming problem as:

 $\begin{array}{rcl} \exists x \ \, \mathbf{A} \cdot \mathbf{x} & = & \mathbf{b} \\ \mathbf{x} & \geq & \mathbf{0} \end{array}$ 

- A basis of the above system is a collection of *m* linearly independent columns.
- **④** A basic solution is obtained by solving the system  $\mathbf{B} \cdot \mathbf{x}_{\mathbf{B}} + \mathbf{N} \cdot \mathbf{x}_{\mathbf{N}} = \mathbf{b}, \mathbf{x}_{\mathbf{N}} = \mathbf{0}$ .
- The basic solution is feasible if every element of x<sub>B</sub> is non-negative.
- The above system is feasible if and only if it has a basic feasible solution.

### Complexity

#### **Fundamentals**

- Assume that A has m rows and n columns.
- Observe that with the introduction of slack variables, we can rewrite the Linear programming problem as:

 $\begin{array}{rcl} \exists x \ \mathsf{A} \cdot x & = & \mathsf{b} \\ & x & \geq & \mathsf{0} \end{array}$ 

- A basis of the above system is a collection of *m* linearly independent columns.
- **(**) A basic solution is obtained by solving the system  $\mathbf{B} \cdot \mathbf{x}_{\mathbf{B}} + \mathbf{N} \cdot \mathbf{x}_{\mathbf{N}} = \mathbf{b}$ ,  $\mathbf{x}_{\mathbf{N}} = \mathbf{0}$ .
- The basic solution is feasible if every element of x<sub>B</sub> is non-negative.
- The above system is feasible if and only if it has a basic feasible solution.
- So all that we have to do now is to show that the basic solutions are polynomial in the size of the input.

# Linear Programming theorem

# Linear Programming theorem

### Theorem

Non-deterministic Polynomial Time Computational Complexity

# Linear Programming theorem

#### Theorem

Let  $\mathbf{x} = [x_1, x_2, \dots, x_m, 0, 0, \dots, 0]^T$  be a basic solution of the system

# Linear Programming theorem

#### Theorem

Let  $\mathbf{x} = [x_1, x_2, \dots, x_m, 0, 0, \dots, 0]^T$  be a basic solution of the system

$$\exists x A \cdot x = b$$

$$x \ge 0$$

# Linear Programming theorem

#### Theorem

Let  $\mathbf{x} = [x_1, x_2, \dots, x_m, 0, 0, \dots, 0]^T$  be a basic solution of the system

$$\begin{array}{rcl} \exists \mathbf{x} \ \mathbf{A} \cdot \mathbf{x} &= \mathbf{b} \\ \mathbf{x} &\geq \mathbf{0} \end{array}$$

Then,

$$|x_i| \le m! \cdot \alpha^{m-1} \cdot \beta$$

where,

# Linear Programming theorem

#### Theorem

Let  $\mathbf{x} = [x_1, x_2, \dots, x_m, 0, 0, \dots, 0]^T$  be a basic solution of the system

 $\begin{array}{rcl} \exists x \ \mathsf{A} \cdot x & = & \mathsf{b} \\ & x & \geq & \mathsf{0} \end{array}$ 

Then,

$$|x_j| \le m! \cdot \alpha^{m-1} \cdot \beta$$

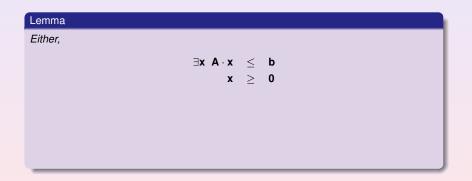
where,

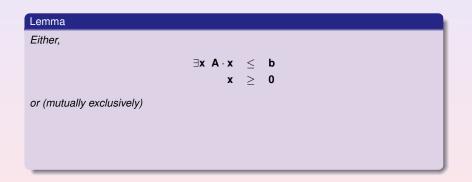
$$\alpha = \max_{i,j} |a_{ij}|$$
$$\beta = \max_{i} |b_{j}|$$

## Farkas' Lemma

#### Lemma

Non-deterministic Polynomial Time Computational Complexity





Lemma	
Either,	
	$\exists x A \cdot x \leq b$
	x ≥ 0
or (mutually exclusively)	
	$\exists \mathbf{y} \ \mathbf{y} \cdot \mathbf{A} \geq 0$
	y ≥ 0
	<b>y</b> · <b>b</b> < 0

# Primality testing

# Primality testing

### PRIMES

Non-deterministic Polynomial Time Computational Complexity

### Primality testing

#### PRIMES

Given a number N, determine whether it is a prime number, i.e., divisible only by one and itself.

### Primality testing

#### PRIMES

Given a number N, determine whether it is a prime number, i.e., divisible only by one and itself.

#### Exercise

### Primality testing

#### PRIMES

Given a number N, determine whether it is a prime number, i.e., divisible only by one and itself.

#### Exercise

Show that PRIMES is in coNP.

## Primality testing

#### PRIMES

Given a number N, determine whether it is a prime number, i.e., divisible only by one and itself.

#### Exercise

- Show that PRIMES is in coNP.
- Output PRIMES is in NP.

## Notations

## Notations

Logarithms and natural numbers

## Notations

Logarithms and natural numbers

Normally, when taking a logarithm, we get a real number.

### **Notations**

### Logarithms and natural numbers

Normally, when taking a logarithm, we get a real number. In order to work with natural numbers, we adopt the following convention:

### Notations

### Logarithms and natural numbers

Normally, when taking a logarithm, we get a real number. In order to work with natural numbers, we adopt the following convention:

 $\log x = \lceil \log_2 x \rceil.$ 

# The Lucas test for primality

# The Lucas test for primality

#### Theorem

Non-deterministic Polynomial Time Computational Complexity

# The Lucas test for primality

#### Theorem

A number p > 1 is prime if and only if and only if there exists a number r,

# The Lucas test for primality

#### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p,

# The Lucas test for primality

#### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p, such that  $r^{p-1} \equiv 1 \mod p$ 

# The Lucas test for primality

#### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p, such that  $r^{p-1} \equiv 1 \mod p$  and furthermore,

# The Lucas test for primality

### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p, such that  $r^{p-1} \equiv 1 \mod p$  and furthermore,  $r^{\frac{p-1}{q}} \neq 1 \mod p$  for all prime divisors q of (p-1).

# The Lucas test for primality

#### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p, such that  $r^{p-1} \equiv 1 \mod p$  and furthermore,  $r^{\frac{p-1}{q}} \neq 1 \mod p$  for all prime divisors q of (p-1).

### Exercise

# The Lucas test for primality

#### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p, such that  $r^{p-1} \equiv 1 \mod p$  and furthermore,  $r^{\frac{p-1}{q}} \neq 1 \mod p$  for all prime divisors q of (p-1).

#### Exercise

Can you design a nondeterministic algorithm for PRIMES?

# The Lucas test for primality

### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p, such that  $r^{p-1} \equiv 1 \mod p$  and furthermore,  $r^{\frac{p-1}{q}} \neq 1 \mod p$  for all prime divisors q of (p-1).

#### Exercise

Can you design a nondeterministic algorithm for PRIMES?

We have to bound the number of prime divisors.

# The Lucas test for primality

#### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p, such that  $r^{p-1} \equiv 1 \mod p$  and furthermore,  $r^{\frac{p-1}{q}} \neq 1 \mod p$  for all prime divisors q of (p-1).

#### Exercise

Can you design a nondeterministic algorithm for PRIMES?

We have to bound the number of prime divisors.

How many prime divisors can p have?

# The Lucas test for primality

#### Theorem

A number p > 1 is prime if and only if and only if there exists a number r, 1 < r < p, such that  $r^{p-1} \equiv 1 \mod p$  and furthermore,  $r^{\frac{p-1}{q}} \neq 1 \mod p$  for all prime divisors q of (p-1).

#### Exercise

Can you design a nondeterministic algorithm for PRIMES?

We have to bound the number of prime divisors.

How many prime divisors can p have? At most log p.

### FUNCTION PRIMALITY CHECKING(p)

1: Guess r.

- 1: Guess r.
- 2: if  $(r^{p-1} \not\equiv 1 \mod p)$  then

- 1: Guess r.
- 2: if  $(r^{p-1} \not\equiv 1 \mod p)$  then
- 3: **return**("no").

```
FUNCTION PRIMALITY CHECKING(p)
```

- 1: Guess r.
- 2: if  $(r^{p-1} \not\equiv 1 \mod p)$  then
- 3: **return**("no").
- 4: **else**

- 1: Guess r.
- 2: if  $(r^{p-1} \not\equiv 1 \mod p)$  then
- 3: **return**("no").
- 4: **else**
- 5: Guess  $q_1, q_2, \ldots q_k$  as the prime divisors of (p 1).

- 1: Guess r.
- 2: if  $(r^{p-1} \not\equiv 1 \mod p)$  then
- 3: return("no").
- 4: **else**
- 5: Guess  $q_1, q_2, \ldots q_k$  as the prime divisors of (p 1).
- 6: **if** (any  $q_i$  is not a prime divisor of (p 1)) **then**

- 1: Guess r.
- 2: if  $(r^{p-1} \not\equiv 1 \mod p)$  then
- 3: return("no").
- 4: **else**
- 5: Guess  $q_1, q_2, \ldots q_k$  as the prime divisors of (p 1).
- 6: **if** (any  $q_i$  is not a prime divisor of (p 1)) **then**

```
7: return("no").
```

### FUNCTION PRIMALITY CHECKING(p)

- 1: Guess r.
- 2: if  $(r^{p-1} \not\equiv 1 \mod p)$  then
- 3: return("no").

### 4: **else**

- 5: Guess  $q_1, q_2, \ldots q_k$  as the prime divisors of (p-1).
- 6: **if** (any  $q_i$  is not a prime divisor of (p 1)) **then**

```
7: return("no").
```

8: end if

```
FUNCTION PRIMALITY CHECKING(p)

1: Guess r.

2: if (r^{p-1} \neq 1 \mod p) then

3: return("no").

4: else

5: Guess q_1, q_2, \dots q_k as the prime divisors of (p-1).

6: if (any q_i is not a prime divisor of (p-1)) then

7: return("no").

8: end if

9: end if
```

```
FUNCTION PRIMALITY CHECKING(p)
 1: Guess r.
 2: if (r^{p-1} \not\equiv 1 \mod p) then
 3:
      return("no").
 4: else
 5:
     Guess q_1, q_2, \ldots, q_k as the prime divisors of (p-1).
      if (any q_i is not a prime divisor of (p-1)) then
 6:
 7:
         return("no").
      end if
 8.
 9: end if
10: for (i = 1 \text{ to } k) do
```

```
FUNCTION PRIMALITY CHECKING(p)
 1: Guess r.
 2: if (r^{p-1} \not\equiv 1 \mod p) then
 3:
      return("no").
 4: else
 5:
     Guess q_1, q_2, \ldots, q_k as the prime divisors of (p-1).
    if (any q_i is not a prime divisor of (p-1)) then
 6:
 7:
         return("no").
      end if
 8.
 9: end if
10: for (i = 1 \text{ to } k) do
11: if (r^{\frac{p-1}{q}} \equiv 1 \mod p) then
```

```
FUNCTION PRIMALITY CHECKING(p)
 1: Guess r.
 2: if (r^{p-1} \not\equiv 1 \mod p) then
 3:
      return("no").
 4: else
 5:
     Guess q_1, q_2, \ldots, q_k as the prime divisors of (p-1).
      if (any q_i is not a prime divisor of (p-1)) then
 6:
 7:
         return("no").
      end if
 8.
 9: end if
10: for (i = 1 \text{ to } k) do
      if (r^{\frac{p-1}{q}} \equiv 1 \mod p) then
11:
12:
         return("no").
```

```
FUNCTION PRIMALITY CHECKING(p)
 1: Guess r.
 2: if (r^{p-1} \not\equiv 1 \mod p) then
 3:
      return("no").
 4: else
 5:
     Guess q_1, q_2, \ldots, q_k as the prime divisors of (p-1).
      if (any q_i is not a prime divisor of (p-1)) then
 6:
 7:
         return("no").
      end if
 8.
 9: end if
10: for (i = 1 \text{ to } k) do
     if (r^{\frac{p-1}{q}} \equiv 1 \mod p) then
11:
12.
    return("no").
      end if
13:
```

```
FUNCTION PRIMALITY CHECKING(p)
 1: Guess r.
 2: if (r^{p-1} \not\equiv 1 \mod p) then
 3:
      return("no").
 4: else
 5:
     Guess q_1, q_2, \ldots, q_k as the prime divisors of (p-1).
    if (any q_i is not a prime divisor of (p-1)) then
 6:
 7:
         return("no").
      end if
 8.
 9: end if
10: for (i = 1 \text{ to } k) do
    if (r^{\frac{p-1}{q}} \equiv 1 \mod p) then
11:
12.
    return("no").
      end if
13:
14: end for
```

```
FUNCTION PRIMALITY CHECKING(p)
 1: Guess r.
 2: if (r^{p-1} \not\equiv 1 \mod p) then
 3.
      return("no").
 4: else
 5:
     Guess q_1, q_2, \ldots, q_k as the prime divisors of (p-1).
      if (any q_i is not a prime divisor of (p-1)) then
 6·
 7:
         return("no").
      end if
 8.
 9: end if
10: for (i = 1 \text{ to } k) do
    if (r^{\frac{p-1}{q}} \equiv 1 \mod p) then
11:
    return("no").
12.
      end if
13:
14: end for
15: return("yes").
```

Algorithm 6.17: A nondeterministic algorithm for PRIMES

# Details

# Details

### Hidden details

Non-deterministic Polynomial Time Computational Complexity

# Details

### Hidden details

• How do we check that the  $q_i$  represent all the divisors of p?

# Details

### Hidden details

**(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.

## Details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- **2** How do we check that the  $q_i$ s are prime?

## Details

- **O** How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- I How do we check that the q<sub>i</sub>s are prime? Recursively!

## Details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- O How do we check that the q<sub>i</sub>s are prime? Recursively! Guess their certificates as well.

## Details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t
- 3 Accordingly, the certificate for *p*, will have the following form:

## Details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t
- 3 Accordingly, the certificate for *p*, will have the following form:



# Details

## Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t
- 3 Accordingly, the certificate for *p*, will have the following form:

 $(r; q_1;$ 

# Details

## Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t
- 3 Accordingly, the certificate for *p*, will have the following form:

 $(r; q_1; C(q_1);$ 

# Details

## Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t
- 3 Accordingly, the certificate for *p*, will have the following form:

 $(r; q_1; C(q_1); q_2;$ 

# Details

## Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t
- 3 Accordingly, the certificate for *p*, will have the following form:

 $(r; q_1; C(q_1); q_2; C(q_2) \dots q_k;$ 

# Details

## Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t
- 3 Accordingly, the certificate for *p*, will have the following form:

 $(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$ 

# Details

### Hidden details

- **1** How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the second se

3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

• Unless p = 2, p will be odd and hence  $q_1 = 2$ .

# Details

### Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- **3** How do we check that the *q<sub>i</sub>*s are prime? Recursively! Guess their certificates as well.
- 3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

# Details

## Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- **3** How do we check that the *q<sub>i</sub>*s are prime? Recursively! Guess their certificates as well.
- 3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

# Details

### Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t
- 3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

# Details

### Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- **3** How do we check that the *q<sub>i</sub>*s are prime? Recursively! Guess their certificates as well.
- 3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

# Details

### Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- **3** How do we check that the *q<sub>i</sub>*s are prime? Recursively! Guess their certificates as well.
- 3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

# Details

## Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- **3** How do we check that the *q<sub>i</sub>*s are prime? Recursively! Guess their certificates as well.

3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

• Unless p = 2, p will be odd and hence  $q_1 = 2$ . So without loss of generality, the certificate for p will have the following form:

 $(r; 2; (1); q_2; C(q_2) \dots q_k;$ 

# Details

### Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- **3** How do we check that the *q<sub>i</sub>*s are prime? Recursively! Guess their certificates as well.

3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

$$(r; 2; (1); q_2; C(q_2) \dots q_k; C(q_k))$$

# Details

### Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- **3** How do we check that the *q<sub>i</sub>*s are prime? Recursively! Guess their certificates as well.

3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

• Unless p = 2, p will be odd and hence  $q_1 = 2$ . So without loss of generality, the certificate for p will have the following form:

 $(r; 2; (1); q_2; C(q_2) \dots q_k; C(q_k))$ 

For instance, the certificate for 67 is:

# Details

## Hidden details

- **(**) How do we check that the  $q_i$  represent all the divisors of p? Repeated division.
- Output the end of t

3 Accordingly, the certificate for *p*, will have the following form:

$$(r; q_1; C(q_1); q_2; C(q_2) \dots q_k; C(q_k))$$

• Unless p = 2, p will be odd and hence  $q_1 = 2$ . So without loss of generality, the certificate for p will have the following form:

 $(r; 2; (1); q_2; C(q_2) \dots q_k; C(q_k))$ 

For instance, the certificate for 67 is:

(2; 2; (1); 3; (2; 2; (1)); 11; (8; 2; (1); 5; (3; 2; (1))).

## Theorem

# Theorem

Let  $\Sigma = \{(, ), 0, 1, ; \}.$ 

# Theorem

Let  $\Sigma = \{(, ), 0, 1, ; \}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

# Theorem

Let  $\Sigma = \{(, ), 0, 1, ; \}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

# Theorem

Let  $\Sigma = \{(, ), 0, 1, ; \}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

### Proof

• Clearly true for p = 2 and p = 3.

## Theorem

Let  $\Sigma = \{(, ), 0, 1, ;\}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

- Clearly true for p = 2 and p = 3.
- 2  $q_1, q_2, q_3, \ldots, q_k$  are prime divisors of (p-1) (  $k \leq \log p$ .).

## Theorem

Let  $\Sigma = \{(, ), 0, 1, ; \}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

- Clearly true for p = 2 and p = 3.
- **2**  $q_1, q_2, q_3, \ldots, q_k$  are prime divisors of (p-1) ( $k \le \log p$ .). Hence,  $q_2 \cdot q_3 \ldots q_k \le \frac{p-1}{2}$ .

## Theorem

Let  $\Sigma = \{(, ), 0, 1, ; \}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

- Clearly true for p = 2 and p = 3.
- ②  $q_1, q_2, q_3, ..., q_k$  are prime divisors of (p 1) (  $k \le \log p$ .). Hence,  $q_2 \cdot q_3 ... q_k \le \frac{p-1}{2}$ .
- Total number of symbols needed to represent r is at most log p.

Let  $\Sigma = \{(, ), 0, 1, ;\}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

- Clearly true for p = 2 and p = 3.
- ②  $q_1, q_2, q_3, ..., q_k$  are prime divisors of (p 1) (  $k \le \log p$ .). Hence,  $q_2 \cdot q_3 ... q_k \le \frac{p-1}{2}$ .
- **③** Total number of symbols needed to represent *r* is at most log *p*.
- Total number of symbols needed to represent 2 and its certificate (1) is 5.

Let  $\Sigma = \{(, ), 0, 1, ;\}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

- Clearly true for p = 2 and p = 3.
- ②  $q_1, q_2, q_3, ..., q_k$  are prime divisors of (p 1) (  $k \le \log p$ .). Hence,  $q_2 \cdot q_3 ... q_k \le \frac{p-1}{2}$ .
- **③** Total number of symbols needed to represent *r* is at most log *p*.
- Total number of symbols needed to represent 2 and its certificate (1) is 5.
- Total number of symbols needed to represent all the  $q_i$ s, i = 2, 3, ..., p is at most  $2 \cdot (\log(\frac{p-1}{2})) \le 2 \cdot (\log p 1)$ .

Let  $\Sigma = \{(, ), 0, 1, ;\}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

- Clearly true for p = 2 and p = 3.
- ②  $q_1, q_2, q_3, ..., q_k$  are prime divisors of (p 1) (  $k \le \log p$ .). Hence,  $q_2 \cdot q_3 ... q_k \le \frac{p-1}{2}$ .
- Total number of symbols needed to represent *r* is at most log *p*.
- Total number of symbols needed to represent 2 and its certificate (1) is 5.
- Total number of symbols needed to represent all the  $q_i$ s, i = 2, 3, ..., p is at most  $2 \cdot (\log(\frac{p-1}{2})) \le 2 \cdot (\log p 1)$ .
- **(**) Total number of symbols needed to represent all the delimiters is  $2 \cdot k \le 2 \cdot \log p$ .

Let  $\Sigma = \{(, ), 0, 1, ;\}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

- Clearly true for p = 2 and p = 3.
- ②  $q_1, q_2, q_3, ..., q_k$  are prime divisors of (p 1) (  $k \le \log p$ .). Hence,  $q_2 \cdot q_3 ... q_k \le \frac{p-1}{2}$ .
- Total number of symbols needed to represent *r* is at most log *p*.
- Total number of symbols needed to represent 2 and its certificate (1) is 5.
- Total number of symbols needed to represent all the  $q_i$ s, i = 2, 3, ..., p is at most  $2 \cdot (\log(\frac{p-1}{2})) \le 2 \cdot (\log p 1)$ .
- **(**) Total number of symbols needed to represent all the delimiters is  $2 \cdot k \le 2 \cdot \log p$ .
- O Total number of parentheses is 2.

Let  $\Sigma = \{(, ), 0, 1, ;\}$ . The size of p's certificate in  $\Sigma$  is at most  $4 \cdot \log^2 p$ .

- Clearly true for p = 2 and p = 3.
- ②  $q_1, q_2, q_3, ..., q_k$  are prime divisors of (p 1) (  $k \le \log p$ .). Hence,  $q_2 \cdot q_3 ... q_k \le \frac{p-1}{2}$ .
- **③** Total number of symbols needed to represent *r* is at most log *p*.
- Total number of symbols needed to represent 2 and its certificate (1) is 5.
- Total number of symbols needed to represent all the  $q_i$ s, i = 2, 3, ..., p is at most  $2 \cdot (\log(\frac{p-1}{2})) \le 2 \cdot (\log p 1)$ .
- **(**) Total number of symbols needed to represent all the delimiters is  $2 \cdot k \le 2 \cdot \log p$ .
- O Total number of parentheses is 2.
- **3** By induction  $|C(q_i)| \le 4 \cdot \log^2 q_i$ .

# Proof

Non-deterministic Polynomial Time Computational Complexity

# Proof

$$C(p)| \leq \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i$$

# Proof

It follows that:

$$\begin{array}{ll} C(p) | & \leq & \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \end{array}$$

i=2

# Proof

$$C(p)| \leq \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{\kappa} \log^2 q_i$$

$$\leq 5 \cdot \log p + 5 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i$$

$$\leq 5 \cdot \log p + 5 + 4 \cdot (\sum_{i=2}^{k} \log q_i)^2$$

# Proof

$$C(p)| \leq \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i$$

$$\leq 5 \cdot \log p + 5 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i$$
  
$$\leq 5 \cdot \log p + 5 + 4 \cdot (\sum_{i=2}^{k} \log q_i)^2$$
  
$$= 5 \cdot \log p + 5 + 4 \cdot \log^2 (q_2 \cdot ... \cdot q_k)$$

# Proof

$$\begin{array}{ll} \mathcal{C}(p)| & \leq & \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot (\sum_{i=2}^{k} \log q_i)^2 \end{array}$$

$$= 5 \cdot \log p + 5 + 4 \cdot \log^2(q_2 \cdot \ldots \cdot q_k)$$
  
$$\leq 5 \cdot \log p + 5 + 4 \cdot (\log \frac{p-1}{2})^2$$

# Proof

$$\begin{array}{ll} \mathcal{C}(p)| & \leq & \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot (\sum_{i=2}^{k} \log q_i)^2 \\ \\ & = & 5 \cdot \log p + 5 + 4 \cdot (\log \frac{p-1}{2})^2 \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot (\log p - 1)^2 \end{array}$$

# Proof

$$\begin{array}{ll} \mathcal{C}(p)| & \leq & \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot (\sum_{i=2}^{k} \log q_i)^2 \\ \\ & = & 5 \cdot \log p + 5 + 4 \cdot (\log^2 (q_2 \cdot \dots \cdot q_k)) \\ \\ & \leq & 5 \cdot \log p + 5 + 4 \cdot (\log p - 1)^2 \\ \\ & \leq & 4 \log^2 p + 9 - 3 \cdot \log p \end{array}$$

# Proof

It follows that:

10

$$\begin{split} \mathcal{D}(p)| &\leq \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ &\leq 5 \cdot \log p + 5 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ &\leq 5 \cdot \log p + 5 + 4 \cdot (\sum_{i=2}^{k} \log q_i)^2 \\ &= 5 \cdot \log p + 5 + 4 \cdot \log^2 (q_2 \cdot \ldots \cdot q_k) \\ &\leq 5 \cdot \log p + 5 + 4 \cdot (\log \frac{p-1}{2})^2 \\ &\leq 5 \cdot \log p + 5 + 4 \cdot (\log p - 1)^2 \\ &\leq 4 \log^2 p + 9 - 3 \cdot \log p \\ &\leq 4 \log^2 p, \end{split}$$

# Proof

It follows that:

10

$$\begin{split} \mathcal{C}(p)| &\leq \log p + 5 + 2 \cdot (\log p - 1) + 2 \cdot \log p + 2 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ &\leq 5 \cdot \log p + 5 + 4 \cdot \sum_{i=2}^{k} \log^2 q_i \\ &\leq 5 \cdot \log p + 5 + 4 \cdot (\sum_{i=2}^{k} \log q_i)^2 \\ &= 5 \cdot \log p + 5 + 4 \cdot (\log^2 (q_2 \cdot \ldots \cdot q_k)) \\ &\leq 5 \cdot \log p + 5 + 4 \cdot (\log \frac{p-1}{2})^2 \\ &\leq 5 \cdot \log p + 5 + 4 \cdot (\log p - 1)^2 \\ &\leq 4 \log^2 p + 9 - 3 \cdot \log p \\ &\leq 4 \log^2 p, \text{ when } p \geq 5. \end{split}$$

# Binary alphabet

# Binary alphabet

How many bits one needs in order to represent p's certificate?

How many bits one needs in order to represent p's certificate?

#### Theorem

Let  $\Sigma' = \{\sigma_1, ..., \sigma_t\}$  be any alphabet with  $|\Sigma'| \ge 2$ , and let x be a string in  $\Sigma'$ .

How many bits one needs in order to represent p's certificate?

#### Theorem

Let  $\Sigma' = \{\sigma_1, ..., \sigma_t\}$  be any alphabet with  $|\Sigma'| \ge 2$ , and let x be a string in  $\Sigma'$ . Then x can be represented using  $|x| \cdot \log |\Sigma'|$  bits,

How many bits one needs in order to represent p's certificate?

#### Theorem

Let  $\Sigma' = \{\sigma_1, ..., \sigma_t\}$  be any alphabet with  $|\Sigma'| \ge 2$ , and let x be a string in  $\Sigma'$ . Then x can be represented using  $|x| \cdot \log |\Sigma'|$  bits, where |x| is the number of symbols from  $\Sigma'$  present in x.

How many bits one needs in order to represent p's certificate?

#### Theorem

Let  $\Sigma' = \{\sigma_1, ..., \sigma_t\}$  be any alphabet with  $|\Sigma'| \ge 2$ , and let x be a string in  $\Sigma'$ . Then x can be represented using  $|x| \cdot \log |\Sigma'|$  bits, where |x| is the number of symbols from  $\Sigma'$  present in x.

#### Corollary

How many bits one needs in order to represent p's certificate?

#### Theorem

Let  $\Sigma' = \{\sigma_1, ..., \sigma_t\}$  be any alphabet with  $|\Sigma'| \ge 2$ , and let x be a string in  $\Sigma'$ . Then x can be represented using  $|x| \cdot \log |\Sigma'|$  bits, where |x| is the number of symbols from  $\Sigma'$  present in x.

#### Corollary

p's certificate requires at most 12 · log<sup>2</sup> p bits.