Integer Programming: Theory and Algorithms

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Outline



- Introduction
- Modeling Logical Constraints

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- Modeling Logical Constraints
- 2 Solving Mixed Integer Linear Programs

- LP Relaxation
- Branch and Bound
- Cutting Planes
- Branch and Cut

Theory of Integer Programming Solving Mixed Integer Linear Programs Introduction Modeling Logical Constraints

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Theory of Integer Programming Solving Mixed Integer Linear Programs

Introduction Modeling Logical Constraints

Reasoning

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Definition (Integer Program)

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$$\begin{array}{rcl} \max z = \mathbf{c} \cdot \mathbf{x} \\ \mathbf{A} \cdot \mathbf{x} &\leq \mathbf{b} \\ \mathbf{x} &> \mathbf{0} \end{array}$$

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In an IP we can model $x_1 \leq 0$ or $-x_1 \leq -5$.

To do this we introduce a new (0, 1)-variable x_2 . The disjunction can now be expressed as:

$$x_1 - M \cdot x_2 \leq 0$$

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This technique can also be used to model constraints like $x_1 \neq 4$.

Exercise

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Construct an IP which models the following problem.

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- Investment 4 requires \$3,400 and has a value of \$4,000.

Theory of Integer Programming Solving Mixed Integer Linear Programs

Introduction Modeling Logical Constraints

Solution

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We get the following IP

 $\max 8 \cdot x_1 + 11 \cdot x_2 + 6 \cdot x_3 + 4 \cdot x_4$

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\max 8 \cdot x_1 + 11 \cdot x_2 + 6 \cdot x_3 + 4 \cdot x_4 \\
6.7 \cdot x_1 + 10 \cdot x_2 + 5.5 \cdot x_3 + 3.4 \cdot x_4 &\leq & 19 \\
& x_1, x_2, x_3, x_4 &\in & \{0, 1\}\end{array}$
Introduction Modeling Logical Constraints

Modeling Restrictions

Introduction Modeling Logical Constraints

Modeling Restrictions

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LP Relaxation Branch and Bound Cutting Planes Branch and Cut

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Example

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Consider the following IP.

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Consider the following IP.

$$\max z = 20 \cdot x_1 + 10 \cdot x_2 + 10 \cdot x_3$$

$$2 \cdot x_1 + 20 \cdot x_2 + 4 \cdot x_3 \leq 15$$

$$6 \cdot x_1 + 20 \cdot x_2 + 4 \cdot x_3 = 20$$

$$x_1, x_2, x_3 \geq 0$$

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However when we consider the original IP we obtain the following as the optimal solution.

$$(x_1, x_2, x_3) = (2, 0, 2) \ z = 60$$

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 - The optimum value for the branch is lower than that of a branch with an integer optimum. (Pruning by *bounds*)

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$\max z = x_1 + x_2$			
$-x_1 + x_2$	\leq	2	
$8 \cdot x_1 + 2 \cdot x_2$	\leq	19	(1)
<i>x</i> ₁ , <i>x</i> ₂	\geq	0	
<i>x</i> ₁ , <i>x</i> ₂	\in	\mathbb{Z}	

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Example

Example

Let us now look at this problem graphically.


Example



Example



Example



Example



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Example

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- Thus, we can create two new systems of constraints:
 - one by adding $x_1 \leq 1$
 - one by adding $x_1 \ge 2$
- We can solve these branches graphically.

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 - Since the optimum solution lower than a known integral solution we also prune this branch.
- All branches are now pruned and we have that the optimum integer solution is $(x_1, x_2) = (1, 3)$ which gives us z = 4.

LP Relaxation Branch and Bound Cutting Planes Branch and Cut

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Figure: Branching Tree

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Solution
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$$(x_1, x_2) = (1.5, 3.5)$$

 $z = 8$

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$$x_{1} \leq 1$$

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$$z = 8$$

$$(x_{1}, x_{2}) = (1, 3)$$

$$z = 6$$

Pruned by integrality

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$$(x_{1}, x_{2}) = (2.125, 1)$$

$$z = 7.375$$

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⁽²⁾

Generating Cutting Planes

Let Constraint (2) be satisfied by the solutions to an MILP with $b \notin \mathbb{Z}$.

$$\sum_{i=1}^{p} a_{i} \cdot x_{i} + \sum_{i=p+1}^{n} a_{i} \cdot x_{i} = b$$
(2)

Let
$$f_0 = b - \lfloor b \rfloor$$
, and let $f_i = a_i - \lfloor a_i \rfloor$ for $i = 1 \dots p$.

Generating Cutting Planes

Let Constraint (2) be satisfied by the solutions to an MILP with $b \notin \mathbb{Z}$.

$$\sum_{i=1}^{p} a_{i} \cdot x_{i} + \sum_{i=p+1}^{n} a_{i} \cdot x_{i} = b$$
(2)

Let $f_0 = b - \lfloor b \rfloor$, and let $f_i = a_i - \lfloor a_i \rfloor$ for $i = 1 \dots p$.

We can now rewrite Constraint (2) as

$$\sum_{i \le p, f_i \le f_0} f_i \cdot x_i + \sum_{i \le p, f_i > f_0} (f_i - 1) \cdot x_i + \sum_{i = p+1}^n a_i = k + f_0.$$

Where $k \in \mathbb{Z}$.

LP Relaxation Branch and Bound Cutting Planes Branch and Cut

Generating Cutting Planes

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Generating Cutting Planes

If $k \ge 0$ then Constraint (2) implies that

$$\sum_{i \le p, f_i \le f_0} \frac{f_i}{f_0} \cdot x_i - \sum_{i \le p, f_i > f_0} \frac{1 - f_i}{f_0} \cdot x_i + \sum_{i = p+1}^n \frac{a_i}{f_0} \ge 1.$$

Generating Cutting Planes

If $k \ge 0$ then Constraint (2) implies that

$$\sum_{i \le \rho, f_i \le f_0} \frac{f_i}{f_0} \cdot x_i - \sum_{i \le \rho, f_i > f_0} \frac{1 - f_i}{f_0} \cdot x_i + \sum_{i = \rho + 1}^n \frac{a_i}{f_0} \ge 1.$$

If $k \leq -1$ then Constraint (2) implies that

$$-\sum_{i\leq p,f_i\leq f_0}\frac{f_i}{1-f_0}\cdot x_i + \sum_{i\leq p,f_i>f_0}\frac{1-f_i}{1-f_0}\cdot x_i - \sum_{i=p+1}^n\frac{a_i}{1-f_0}\geq 1.$$

Generating Cutting Planes

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Since each x_i is non negative we will always have that.

$$\sum_{i \le p, f_i \le f_0} \frac{f_i}{f_0} \cdot x_i + \sum_{i \le p, f_i > f_0} \frac{1 - f_i}{1 - f_0} \cdot x_i + \sum_{i > p, a_i > 0} \frac{a_i}{f_0} - \sum_{i > p, a_i < 0} \frac{a_i}{1 - f_0} \ge 1.$$

Generating Cutting Planes

If $k \ge 0$ then Constraint (2) implies that

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This constraint is known as the Gomory mixed integer cut.

LP Relaxation Branch and Bound Cutting Planes Branch and Cut

Example

P. Wojciechowski Optimization Methods in Finance

LP Relaxation Branch and Bound Cutting Planes Branch and Cut

Example

Let us return to System (1).

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Adding slack and surplus variables yields the system

LP Relaxation Branch and Bound Cutting Planes Branch and Cut

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 $\max z = x_1 + x_2$ -x₁ + x₂ + x₃ = 2 8 · x₁ + 2 · x₂ + x₄ = 19 x₁, x₂, x₃, x₄ ≥ 0 x₁, x₂, x₃, x₄ ∈ Z

LP Relaxation Branch and Bound Cutting Planes Branch and Cut

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LP Relaxation Branch and Bound Cutting Planes Branch and Cut

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Using the simplex method we get the following at the linear optimum,

$$z = 5 - 0.6 \cdot x_3 - 0.2 \cdot x_4$$

$$x_1 = 1.5 + 0.2 \cdot x_3 - 0.1 \cdot x_4$$

$$x_2 = 3.5 - 0.8 \cdot x_3 - 0.1 \cdot x_4$$

LP Relaxation Branch and Bound Cutting Planes Branch and Cut

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We can now use the constraint $x_2 + 0.8 \cdot x_3 + 0.1 \cdot x_4 = 3.5$ to generate a Gomory mixed integer cut.

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Example

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Example

Use the constraint $x_2 + 0.8 \cdot x_3 + 0.1 \cdot x_4 = 3.5$ to generate a Gomory mixed integer cut we get the constraint

$$\frac{1-0.8}{1-0.5} \cdot x_3 + \frac{0.1}{0.5} \cdot x_4 \ge 1.$$

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Since $x_3 = 2 + x_1 - x_2$ and $x_4 = 19 - 8 \cdot x_1 - 2 \cdot x_2$ this constraint is equivalent to

$$3 \cdot x_1 + 2 \cdot x_2 \ge 9.$$

Theory of Integer Programming Solving Mixed Integer Linear Programs LP Relaxation Branch and Bound Cutting Planes Branch and Cut

Example

Example

Let us now look at this problem graphically.



Figure: Graphical Solution

Example



Example



Example



Example



Example



Theory of Integer Programming Solving Mixed Integer Linear Programs LP Relaxation Branch and Bound Cutting Planes Branch and Cut

Outline

- Theory of Integer Programming
 - Introduction
 - Modeling Logical Constraints
- 2 Solving Mixed Integer Linear Programs

- LP Relaxation
- Branch and Bound
- Cutting Planes
- Branch and Cut

Definition (Branch and Cut)

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• Branch an Cut is a combination of branch and bound and cutting planes.

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- Branch an Cut is a combination of branch and bound and cutting planes.
- This method proceeds just like regular branch and bound except that at each branch the LP is strengthened using cutting planes.